A New Approach to IEEE1588



The Synchronization Experts.

Applying a Client/Server Model to Unicast PTP as an Alternative to NTP

Improve Efficiency Reduce Complexity

Enhance Security Maintain Accuracy

Designed to improve efficiency while reducing complexity, this new approach to IEEE1588 modifies unicast PTP to enable it to adopt a client/server model, while maintaining—or even improving on—the achievable synchronization accuracy by combining the hardware timestamping capabilities of PTP with certain aspects of the clock filtering, selection, and combining algorithms provided by NTP.

The client/server-based communication flow of this new concept allows it to adopt established security technologies such as NTS (Network Time Security) ordinarily used for NTP for the purpose of authenticating PTP messages exchanged between clients and servers—potentially a game changer when it comes to PTP traffic security.

How It Works	How It Performs	How It Performs			
Sorvor	- 1-PPS Reference	Test Setup			



Sync Request

The client sends Sync and Follow Up Messages (assuming that Two-Step mode is running) with a Request TLV attached to either of them.

t1 Sync Message egress timestamp (Client) **t2** Sync Message ingress timestamp (Server)

Sync Response

Upon receipt of a complete Sync Request sequence, the server responds with Sync and Follow Up Messages (again, assuming Two-Step mode) with a Response TLV attached to the same message as in the Request sequence.

t3 Sync Message egress timestamp (Server) **t4** Sync Message ingress timestamp (Client)

PTP Message Header

Request TLV

Field	Octets	TLV Offset	Value	Field	k	Valu	le
tlvType	2	0	3 (ORG_EXT)	majorSdold	messageType	0	see IEEE1588
lengthField	2	2	36+N	minorVersionPTP	versionPTP	1	2



In the test setup, we used three PC Engines APU.2E4 SBCs as DUTs: one as a client (C1) and two as servers (S1+S2). These SBCs have three Intel i210-AT NICs, each with its own PTP hardware clock (PHC).

A laptop running Ubuntu Linux acted as a software router (R1) between the client and servers.

The servers and the PPS analyzer board provided by NetTimeLogic GmbH shared a GNSS synchronized 1-PPS reference clock.

In each of our test scenarios, we ran both ptp4I and flashptpd for at least 3600 seconds (1 hour), one after the other, before comparing the measurements, see results below.

ptp4l

flashptpd

1) Direct (L2) Connection – Small Delay, No Jitter

Both ptp4I as well as flashptpd adjusted the PHC to a very stable and small offset of -8 to +24ns.



organizationId	3	4	0xEC4670
organizationSubType	3	7	0x526571
flags	4	10	
pad	22+N	14	Ο

Response TLV

Field	Octets	TLV Offset	Value
tlvType	2	0	3 (ORG_EXT)
lengthField	2	2	36+N
organizationId	3	4	0xEC4670
organizationSubType	3	7	0x526573
flags	4	10	
error	2	14	
reqIngressTimestamp	10	16	
reqCorrectionField	8	26	
utcOffset	2	34	
bmcaComparisonDS	O+N	36	

messageLength	see IEEE1588			
domainNumber	0			
minorSdold	0			
flagField	see IEEE1588			
correctionField	0			
messageTypeSpecific	0			
sourcePortIdentity	see IEEE1588			
sequenceld	see IEEE1588			
controlField	see IEEE1588			
logMessageInterval	Req.: Interval (log ₂), Resp.: 0x7f			
Mean Path Delay				
(t2 - t1 + t4 - t3) / 2				
<u>Offset</u>				
(t2 + t3 – t1 - t4) / 2				



2) Routed Connection - 30 to 750µs Delay, up to 300µs Jitter

While ptp4I kept the PHC within around +/-60µs (even with high message rates and small PI proportional and integral constants), flashptpd adjusted the PHC to a pretty stable offset of -5 to +3µs.



3) Routed Connection – 40 to 75ms Delay, up to 20ms Jitter

When emulating the properties of a WAN by adding delay and jitter, ptp4l kept the PHC roughly within -2 and +2.8ms, while flashptpd was able to stay well within +/-1ms.













Our reference implementation flashptpd used for the presented test scenarios and measurements is free and open-source (MIT License).

Please feel free to download, test, or contribute:

https://github.com/thomas-behn/flashptpd







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