Terrestrial Timing System

SECURE, RESILIENT SOLUTION FOR POSITION, NAVIGATION, AND TIMING





Agenda

- > Need for resilient timing
- > TerraPoiNT system
- > Network and beacon timing
- > Timing in urban areas with multiple hops
- > Trials and results
- > Conclusion



Resilient Timing

- Timing has become critical for major infrastructure and requires a resilient timing system
 - Most of the timing systems utilize GNSS receivers to derive and provide timing information
- GNSS-based Timing systems are susceptible to the following problems:
 - Low GNSS signal strength creates constraints in antenna placement & cable calibration
 - Easily prone to interference: weak signals can be easily jammed
 - Spoofing: Various incidents have indicated that GPS system is vulnerable to spoofing which can cause more damage than undesired interference
- The NextNav TerraPoiNT system provides a better timing solution that overcomes the challenges of existing systems



System Attributes

- Provides full position, navigation and timing capabilities in urban and indoor environments with or without the presence of GPS
 - Timing only services offered with 1-2 beacon overlap
 - Full PNT services with 4 beacon overlap
 - Resilient timing and operation in absence of GPS
- "Mission critical" reliability: support for an encrypted signal and resistant to spoofing/jamming
- Nationwide spectrum owner (920 928 MHz) 95% urbanized POPs
- Supported in global cellular standards 3GPP (Rel. 13+) and OMA (SUPL 2.0.3) as "MBS", a type of terrestrial beacon system (TBS), as well as at other SDOs
- PNT IC based capability available from 1H 2022



System Architecture

- Beacons deployed throughout the coverage area
- Each beacon has an **onboard timing source**
- Beacons share time with each other to maintain local synchronization
- UTC sync to a small subset of beacons can be provided using:
 - Any absolute alternate timing source (eg. ToF, LEO satellite, TWSTT) and can also be maintained across outages using a local Cesium.
 - Or... holdover from GNSS maintained using local Cesium during GNSS outages
- **Signal is encrypted** to enable user authentication and to provide a level of spoofing protection



Resilient mesh architecture:

if any beacon is compromised, the service will continue



Timing Fusion Technology

Leader Beacon



- Can accept multiple absolute time sources: i.e GPS, Time-Over-Fiber (TOF), Low-Earth Orbit satellites
- Rb atomic clock provides ST-2 holdover and ability for an extended holdover source such as Cesium



Follower Beacon



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- All beacons have a two-way time transfer receiver synchronizing through measured paths from other beacons
- Follower-Leader timing is maintained through two-way timetransfer based corrections
- Follower control loop with mix of centralized and distributed control which applies the corrections to the Rb clock



* Note that the beacon can operate completely GPS free

Mesh Network Wireless Sync of Beacons

- The network is a mesh of beacons (transmitters) consisting of Leader beacon(s) and Follower beacons
 - Leader beacon(s) have access to one or more absolute time sources (UTC)
 - Follower beacons listen to one or more Leader and Follower beacons, and compute ToA measurements for time transfer purposes
- **TWTT technology** is used to take ToA measurements and compute synchronization information for each beacon



APNT Demo Network

at SJ



Time transfer over multiple-hops

- In a network, the follower beacon can derive timing using another follower resulting in multiple hops to synchronize the beacon with leader which has the UTC time
 - The mean of the time transfer error between a pair of beacons (one hop) can be positive or negative
 - When time is transferred across multiple hops, the cumulative mean time error need not grow always. However, the variance of time error grows as the number of hops increase
 - TerraPoiNT network can have multiple time transfer beacon paths where the best path can be preselected during installation or dynamically to get minimum time error growth
- In this APNT network, the follower beacons were able to maintain time within 10ns of the absolute time



Time Distribution Demonstration

- A network of 4 beacons in SanJose (SJ) downtown:
 - Leader, Follower 1 (F1), Follower 2 (F2) and Follower 3 (F3)
 - F1 follows Leader, F2 follows F1 and F3 follows F2 beacon.
- Total time transfer distances:
 - − First hop distance (L \rightarrow F1) is 5.13 km
 - Two-hop distance (L \rightarrow F1 \rightarrow F2) is 12.7 km
 - Three-hop distance (L \rightarrow F1 \rightarrow F2 \rightarrow F3) is 16.24 km
- **Two test locations**, in challenging indoor environments
- NextNav Timing Receiver (NTR) configured to track F1, F2 or F3 depending on the scenario.

Network and Test Sites



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Demo Timing Receiver Capabilities

- Provides HW based PPS + 10MHz + time of day (TOD) message including residual time corrections
- Performs self-survey or accepts pre-surveyed location as input
- Automatically selects the best beacon signal for extracting timing
- Based on an OCXO

- Present receiver takes ~10 minutes to provide a valid PPS output after the receiver is configured/powered-on
- Configuration and monitoring is through a serial port



Demo Performance Assessment Methodology @ Timing Receivers

- Timing receiver is used in this demo to derive timing from a specific beacon
- Performance of the receiver against timing truth is measured using Calnex or an equivalent system
- The Calnex or equivalent system measures and displays the time error of timing receiver pps with respect to timing truth







Test Setup at Site 1

The test location is in San Jose downtown



Antenna for timing receiver

The timing receiver and its antenna are located inside a sheltered equipment room on the top floor of a 14-story building.







Test Setup at Site 2

The test location is in San Jose downtown.



The timing and its antenna are located inside the office space, on the 8th floor of a 12-story building.

The office is in a deep indoor location, ~25 ft from the window.









Results @ Test Sites

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• Short Term tests over 1 hour duration were

High accuracy @ errors well under 100 ns

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Long Term Test

- A test was performed over 72 hour long to determine the performance over a long term
- The results indicate absolute accuracy within 50ns
- This indicate TerraPoiNT timing is stable over long term





Beacon Time Sync Performance

Beacon timing compared to the GPS Timing truth



Followers track the Leader

Timing errors within [-15 ns to +15 ns]



Conclusions

- Demonstration showed a functional, stable and high precision timing system that is independent of GPS, in a real-world environment
- Time transfer system, combined with a Cesium clock or other time source can deliver high precision timing wirelessly across a wide coverage area
- The demonstration showed **the system can accept multiple time references and maintain relative and absolute sync** across the beacon network and in a robust manner
- Beacon network timing for end user timing applications was delivered in difficult urban environments using a timing receiver accurate within 50ns, which could be built with the same form factor as a GPS chipset-based solution
- Demonstration shows the TerraPoiNT system provides the capability to distribute the UTC time wireless with accuracy required to support applications such as 5G time sync, timing for automotive applications

