

Testing Telecom Packet Clocks (G.8273)

WSTS 2014, San Jose

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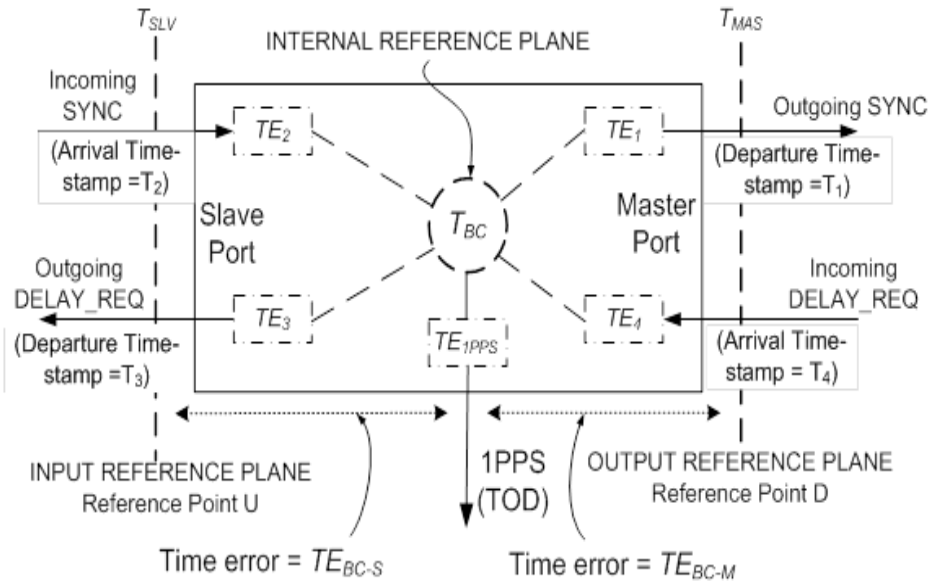
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- ▶ Testing Telecom Packet Clocks
 - ▶ Focus on phase/time performance
 - ▶ Protocol not addressed here
- ▶ Test Principles (G.8273 Annex A)
- ▶ Testing Configurations (G.8273 Annex B)
- ▶ Concluding Remarks
- ▶ (Back-up slides for information)

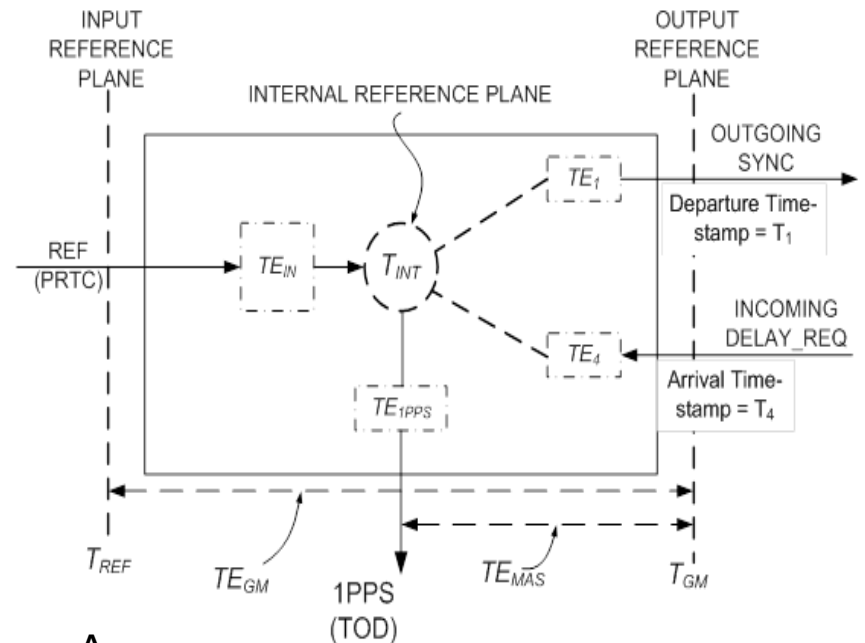
Testing PTP (Packet) Clocks

- ▶ Packet based phase/time clocks G.8273
 - ▶ Grandmaster Clocks (T-GM).... G.8273.1
 - ▶ Could be integrated with a PRTC (G.8272)
 - ▶ Boundary Clocks (T-BC).... G.8273.2
 - ▶ Transparent Clocks (T-TC).... G.8273.3
 - ▶ Slave Clocks (T-TSC).... G.8273.4
 - ▶ Variations based on whether for full-timing-support case or not
- ▶ Types of Ports
 - ▶ Master ports (T-GM, T-BC)
 - ▶ Slave ports (T-BC, T-TSC)
 - ▶ I/O ports (T-TC)
- ▶ Considerations for synchronization may be different for time/frequency

Testing Master Ports (BC & GM)



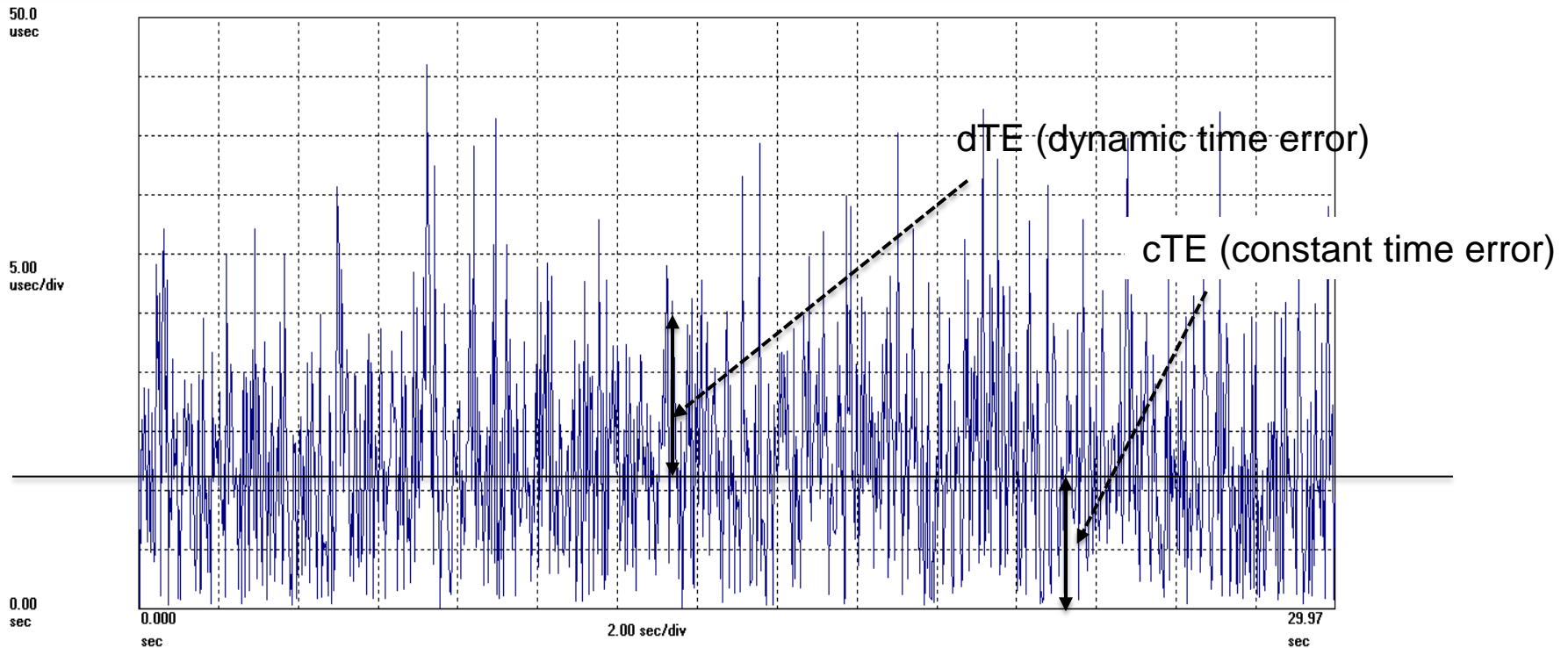
Grandmaster clock: local time-clock developed using a PRTC reference (external or integrated)



Boundary clock: local time-clock developed using a slave clock synchronized to an upstream grandmaster clock

Diagram showing breakdown of constant/dynamic time error

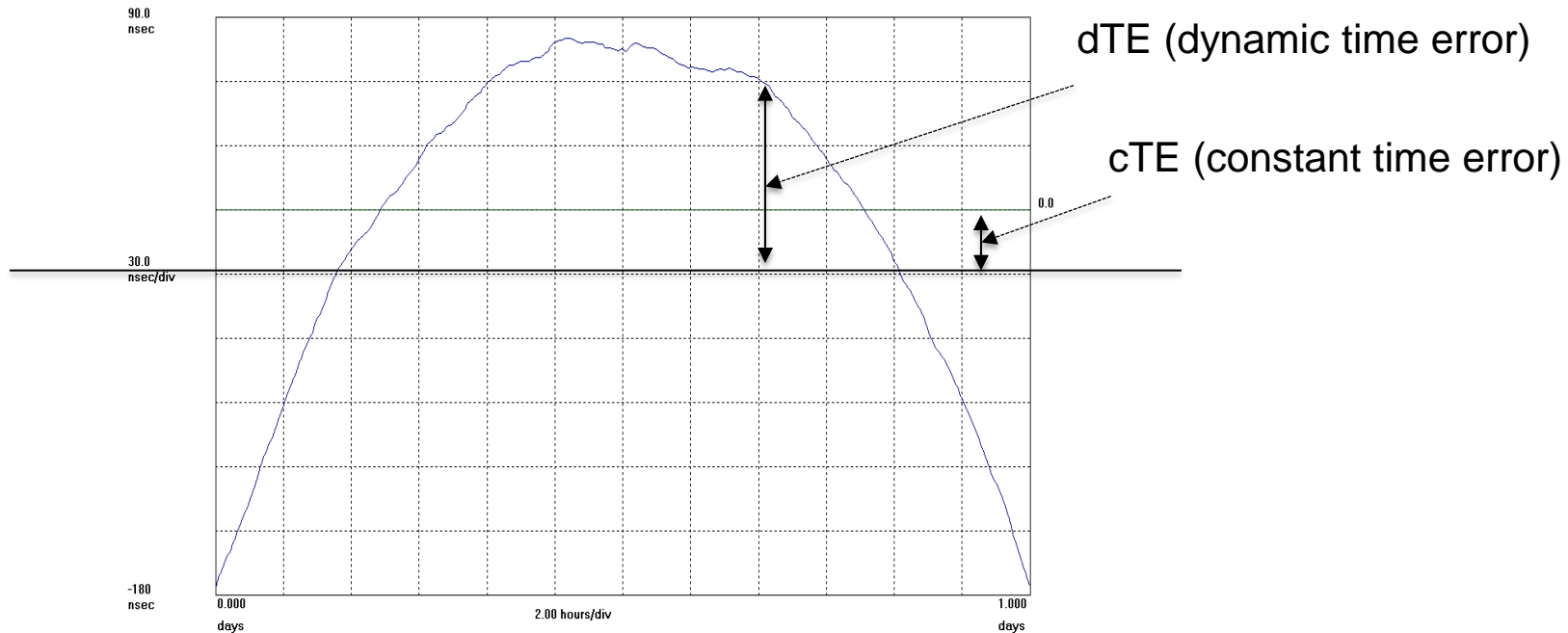
Time error of clock (or time-stamp value) measured against reference



cTE: constant time error analogous to “dc” component
dTE: dynamic time error analogous to “ac” component

Diagram showing breakdown of constant/dynamic time error

Time error of clock measured against reference



cTE: constant time error analogous to “dc” component.

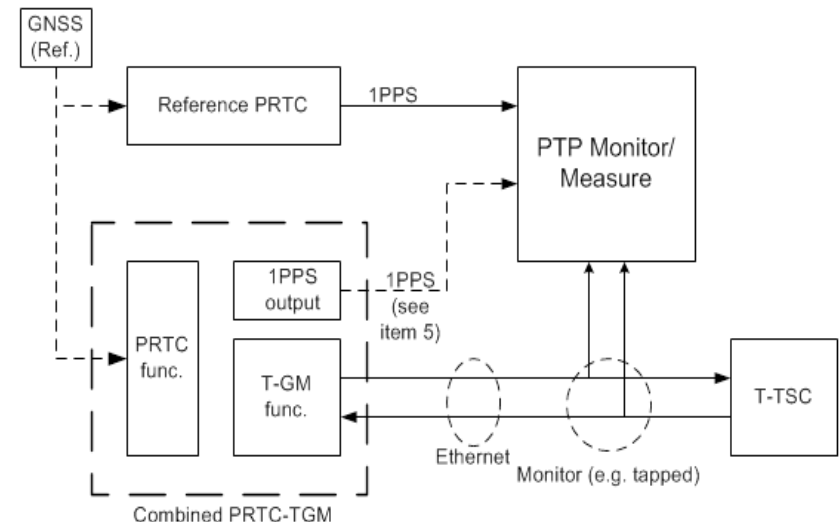
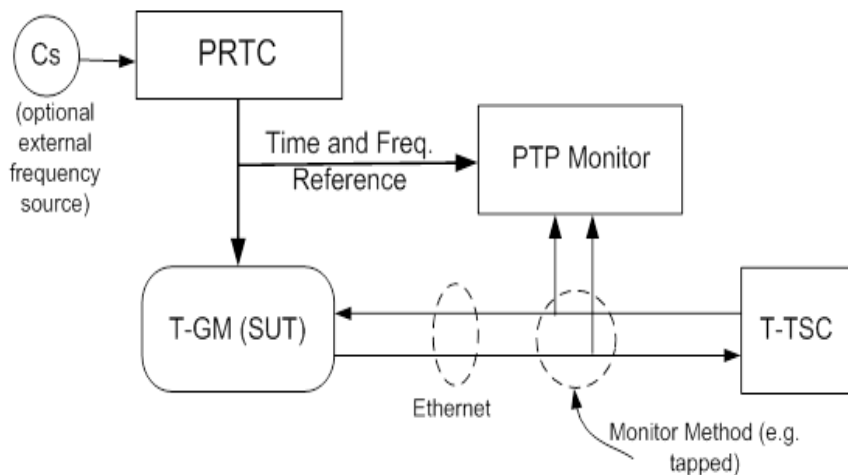
Estimating cTE as an average requires an adequate observation interval.

Testing Master Ports (Equipment)

- ▶ Two key parameters (G.8273 Annex A):
 - ▶ Time-stamp error (TSE)
 - ▶ “Does the time-stamp reflect the true time-clock of the device”?
 - ▶ Time-stamp errors: $|TE_1|$ and $|TE_4|$
 - ▶ TE_1 : error in time-stamp of *Sync Message*
 - ▶ TE_4 : error in time-stamp of *Delay_Request Message*
 - ▶ Can be performed on individual packets
 - ▶ **Note**: time-stamp value involves multiple fields
 - ▶ Time-transfer error (TXE)
 - ▶ “Is device capable of delivering proper time synchronization to a downstream slave”?
 - ▶ Time-transfer error proportional to $|TE_1 - TE_4|$
 - ▶ Extra signal processing involved to address impact of different rates and time-alignment of *Sync* and *Delay_Request* packets

Testing Master Ports

- ▶ Example Test Configurations (G.8273 Annex B)
 - ▶ T-GM could have external PRTC or integrated PRTC
 - ▶ The cable length between the T-GM and the monitoring tap must be calibrated
- ▶ Measurement
 - ▶ Observe time-of-passage of packet at monitor point
 - ▶ Compare with value from time-stamp fields to establish time-stamp “error” (TE_1 and TE_4)

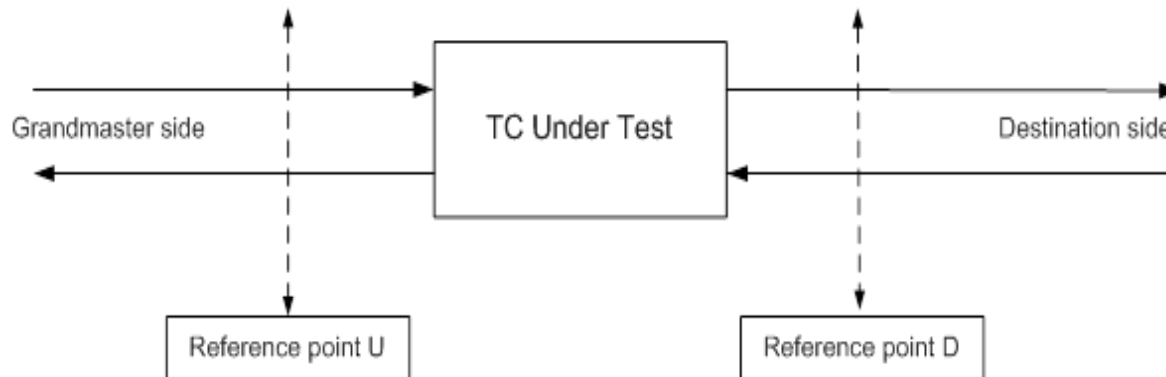


(Figures from G.8273 Annex B)

Testing Transparent Clocks

- ▶ Change in correction field(s) should equal residence time
- ▶ Thus effective time change = zero (nominally) after correction
- ▶ Time (using a “golden slave”) at reference point U and at reference point D should be equal

G.8273 Annex A

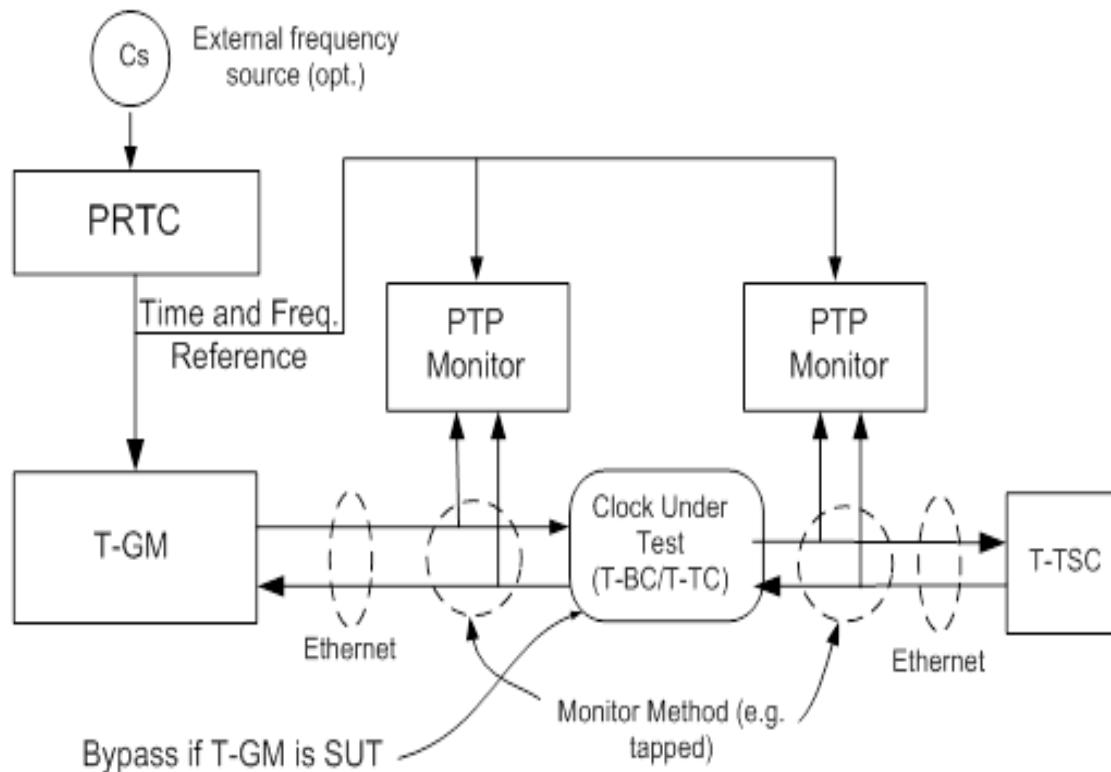


$$|T_U(t) - T_D(t)| < X_{TC} \text{ (ns)}$$

X_{TC} = maximum allowable error

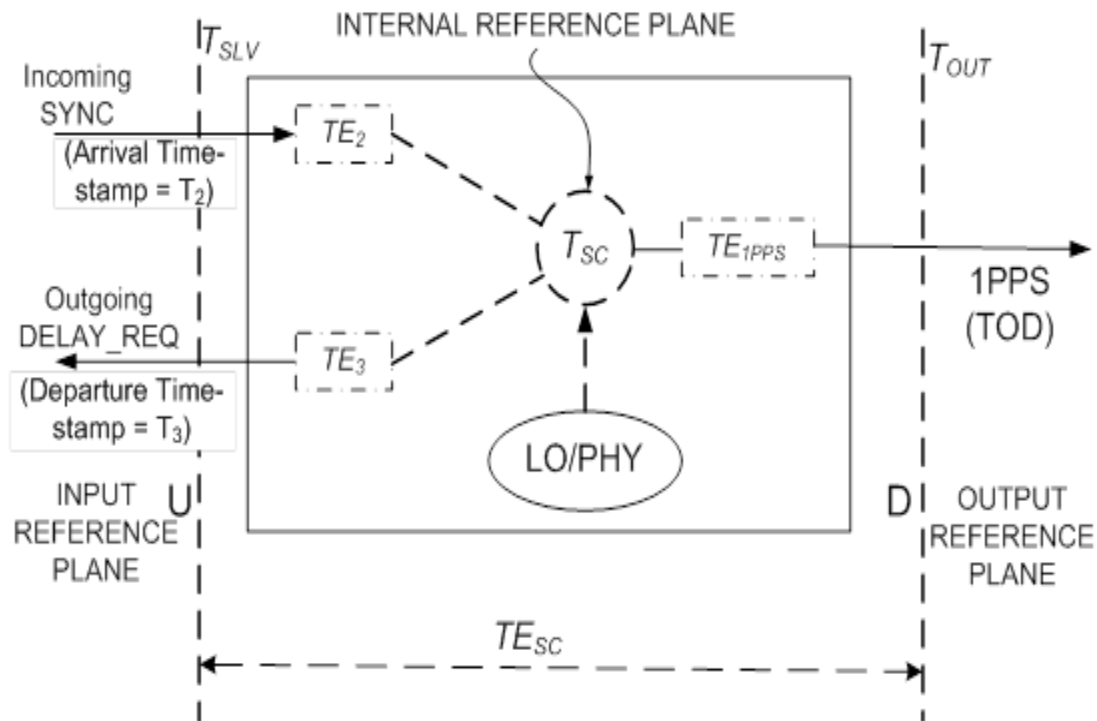
Testing Transparent Clocks

- ▶ Test Configuration example (G.8273 Annex B)



Testing Slave Ports

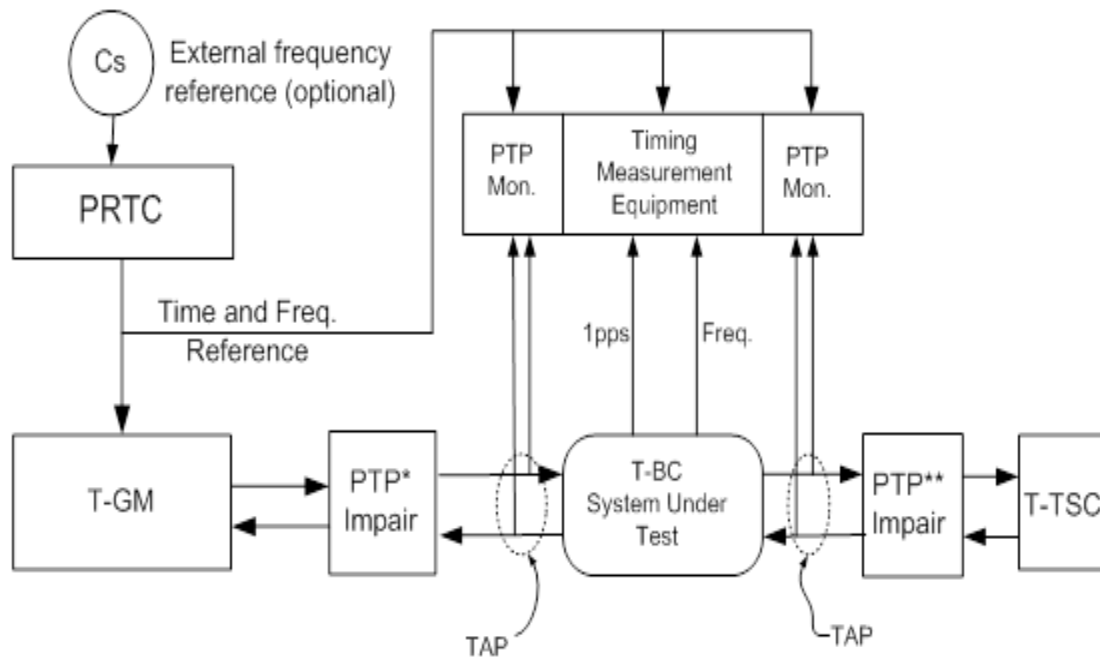
- ▶ Principal performance parameters (G.8273 Annex A)
- ▶ Time-stamp errors TE_2 and TE_3 not generally visible externally
- ▶ T_{SLV} = time using an ideal slave at input reference plane (U)



- For network limit examine $|T_{OUT}|$
- For generation examine $|T_{OUT} - T_{SLV}|$
- Slave time-clock via 1PPS(+TOD) for T-BC and T-TSC

Testing Slave Ports

- ▶ Testing Configuration (G.8273 Annex B)
- ▶ Time error visible via the 1pps output (T-BC and T-TSC)

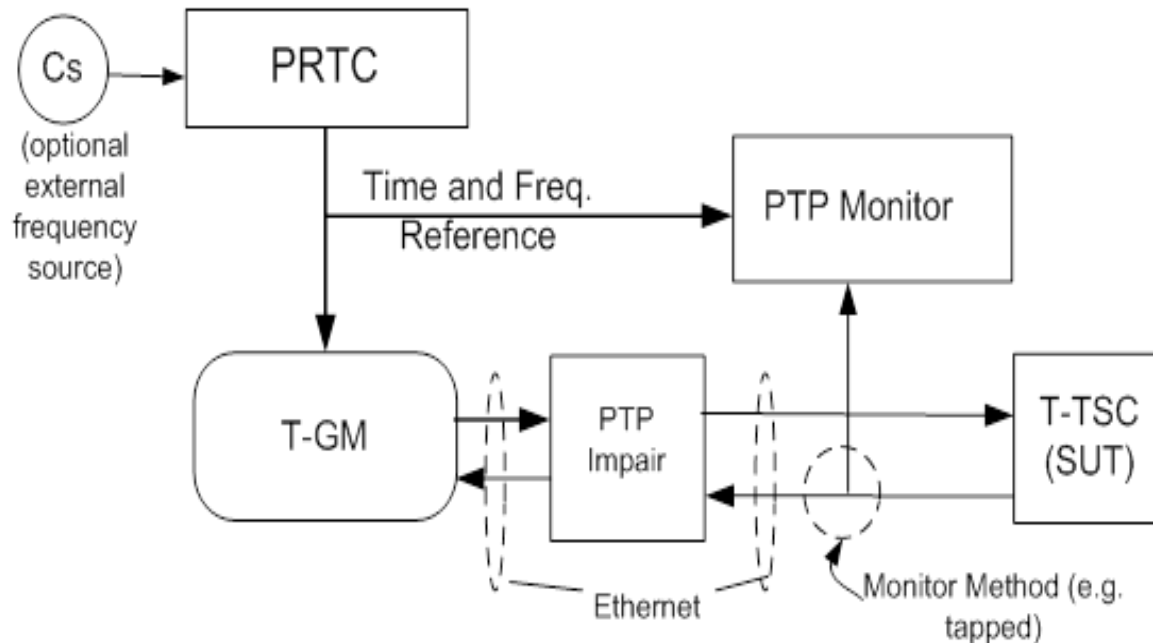


* : See note (b)

** : See note (c)

Testing Slave Ports

- ▶ Testing Configuration (G.8273 Annex B)
- ▶ Slave clock time error visible if precise value of T_3 provided in *delay_request* message or subsequent (not-standardized) follow-up message



Computing Metrics

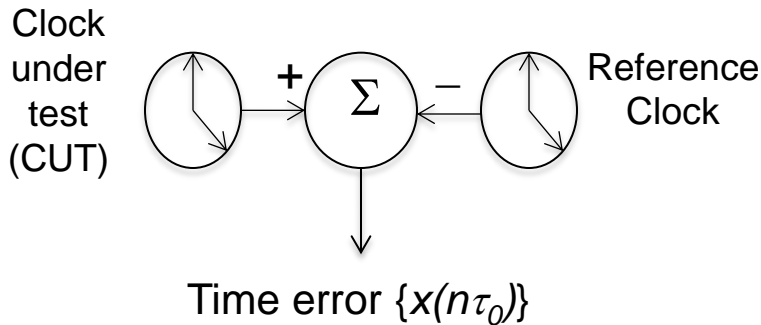
- ▶ For a measured time error sequence $\{x(n)\}$ or filtered time error sequence $\{y(n)\}$ (commonly proposed filter: 0.1Hz):
 - ▶ Max (absolute) time error : $|x(n)|_{\max}$
 - ▶ cTE... estimate of constant time error: average of N samples
 - ▶ Max (absolute) filtered time error : $|y(n)|_{\max}$
 - ▶ MTIE... maximum (absolute) time interval error (stability metric)
 - ▶ TDEV... stability metric that describes power (and type) of noise
 - ▶ MATIE... maximum (absolute) averaged time interval error
 - ▶ MAFE... related to MATIE
 - ▶ TEDEV... standard deviation of averaged time interval error
 - ▶ Other [TBD; e.g. percentile values for maximum and minimum (floor)]

Special Considerations

- ▶ Measuring time error (static and dynamic) increasing in importance
 - ▶ “Frequency” metrics (PDV) necessary but not sufficient (ignore cTE)
- ▶ Boundary clocks (and transparent clocks) are not perfect
 - ▶ Effectively introduce static as well as PDV-like (dynamic) timing impairments (time error)
- ▶ Reason for impairments may be implementation dependent
 - ▶ Behavior affected by sync rates and traffic loads
- ▶ Testing during equipment development phase is very helpful
- ▶ Test Equipment measurement granularity must be substantively better than expected clock behavior
- ▶ For measuring transit delay the time-stampers (test equipment) at “U” and “D” must be synchronized to each other

Thank You!
Questions?

Back-up Slides



Clock
Error
model

$$x(n\tau_0) = a_0 + \eta \cdot (n \cdot \tau_0) + \varphi(n \cdot \tau_0)$$

a_0 : constant time error

η : frequency offset

φ : Noise terms (“random”)

- ▶ Metrics establish “strength” of time error. Different metrics focus on different aspects of this “strength”.
- ▶ Maximum absolute time error : $|x(n\tau_0)|_{\max}$ is the overarching time error metric (maximum over all time)
- ▶ First difference eliminates a_0 : strength of $\{x(n+k) - x(n)\}$ quantifies stability of the time error
 - ▶ Variations include MTIE, MATIE, TEDEV
- ▶ Second difference eliminates η and a_0 : strength of $\{x(n+2k) - 2x(n+k) + x(n)\}$ quantifies stability of the frequency (e.g. TDEV, ADEV, MDEV)

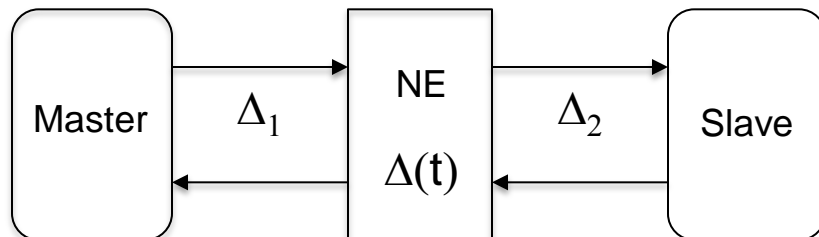
Metrics Mathematics

- ▶ Possible to separate “high-band” and “low-band” time error by filtering $\{x(n)\}$ to get $\{y(n)\}$
 - ▶ Identifies the component that could be in the pass-band of the down-stream clock
 - ▶ Reasonable choice of cut-off frequency = 0.1Hz
- ▶ Some metrics include an average over one observation interval (k samples) that is incorporated into the formula
 - ▶ MATIE, TEDEV, TDEV, MDEV

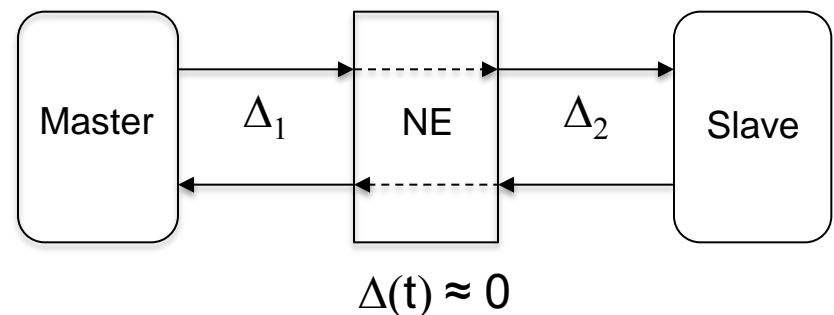
Principles of on-path support

- ▶ Time transfer accuracy bounded from below by transit delay asymmetry (Δ_1 and Δ_2)
- ▶ Frequency transfer accuracy impaired by transit delay variation
- ▶ On-path support attempts to:
 - ▶ Minimize (eliminate) transit delay asymmetry in NE
 - ▶ Minimize (eliminate) transit delay variation in NE
 - ▶ Time transfer error is minimized [$\geq (\Delta_1 + \Delta_2)$]

PTP-unaware Network Element

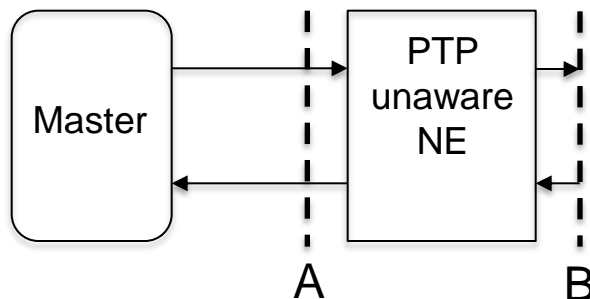


PTP-aware Network Element

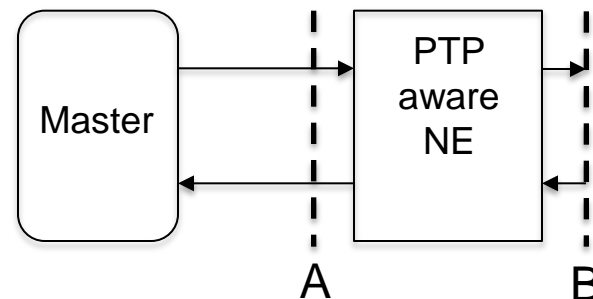


Principles of on-path support

- ▶ Consider (hypothetical) slave deployed just before or just after NE
 - ▶ *Without* on-path support the slave at B has *different* time/wander behavior compared to the slave at A; performance is load dependent
 - ▶ *With* on-path support the slave at B has (ideally) the *same* time/wander behavior compared to the slave at A; performance *should be load independent*
- ▶ Two forms of on-path support:
 - ▶ Boundary clock — “regenerates” master
 - ▶ Transparent clock — acts “invisible” (by providing correction)



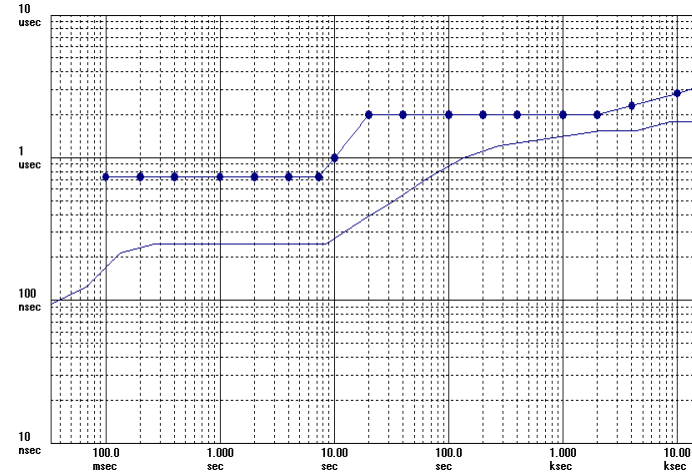
Slave at A \neq Slave at B



Slave at A \approx Slave at B

“What To Test” for PTP Equipment

- ▶ G.8261 Test Cases
 - ▶ PDV of network emulated using precise profiles with Anue 3500 or Calnex Paragon
 - ▶ Wander on the recovered clock of slave is evaluated according to the ITU-T standards (MTIE & TDEV)
- ▶ Time Error & Phase
 - ▶ Compare 1PPS of master with slave
 - ▶ LTE requirement: <math><1.5\mu\text{s}</math>
 - ▶ Measure PTP packet time error
 - ▶ Boundary Clock timestamp accuracy (time error)
 - ▶ Grandmaster Clock timestamp accuracy (time error)
 - ▶ Transparent Clock correction field accuracy

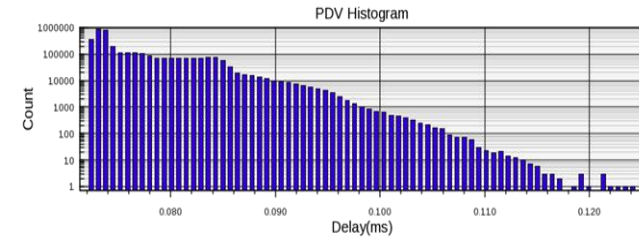


MTIE Plot example

- Top line is mask
- Bottom line is measured TIE
- Staying below the mask indicates a “pass”

Testing to G.8261

- ▶ **Slave Clock (aka Ordinary Clock) Functionality**
 - ▶ Receives timestamps from sync and follow-up packets from master
 - ▶ Calculates network delay using delay request, delay response sequence
 - ▶ Delivers the recovered clock to the host or network
 - ▶ PDV in the network affects recovered clock accuracy



- ▶ **Boundary Clock Functionality**
 - ▶ Potential for timestamp error – same effect as PDV
 - ▶ Caused by: queuing delays, inaccurate clock recovery, network congestion, etc.

- ▶ **Transparent Clock Functionality**
 - ▶ Potential for correction field error
 - ▶ Inaccuracy in the correction field can reduce the effectiveness of the transparent clock to remove the cumulative effects of PDV

Delay Stats (ms)		
	Delay	Time
Minimum	0.072	00:07:38
Maximum	0.124	00:16:02
Average	0.076	

- ▶ Monitoring/measuring time error on both sides of a boundary/transparent clock
 - ▶ Comparison between input and output reveals the static and dynamic impact of the device and we can verify whether it is affected by
 - ▶ Background traffic, incoming and outgoing sync packet interval, QoS, routing, etc
- ▶ Impairment on both sides of a boundary/transparent clock
 - ▶ Impairment is added between the GM Clock and BC/TC, and between the BC/TC and slave clock, simultaneously; recovered clock at remote slave is measured
 - ▶ Profiles need to be developed
- ▶ Measure ToD error and phase (1PPS) error introduced by boundary clocks
 - ▶ Monitor and measure timestamp accuracy of sync, follow-up packets from master port of boundary clock and measure phase offset of 1PPS between GM Clock and Slave with boundary clock in between

Thank You!



Further Questions?

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