

Timing Reference Sources

Tutorial March 9 ahead of WSTS, March 10-12, 2015

San Jose, CA



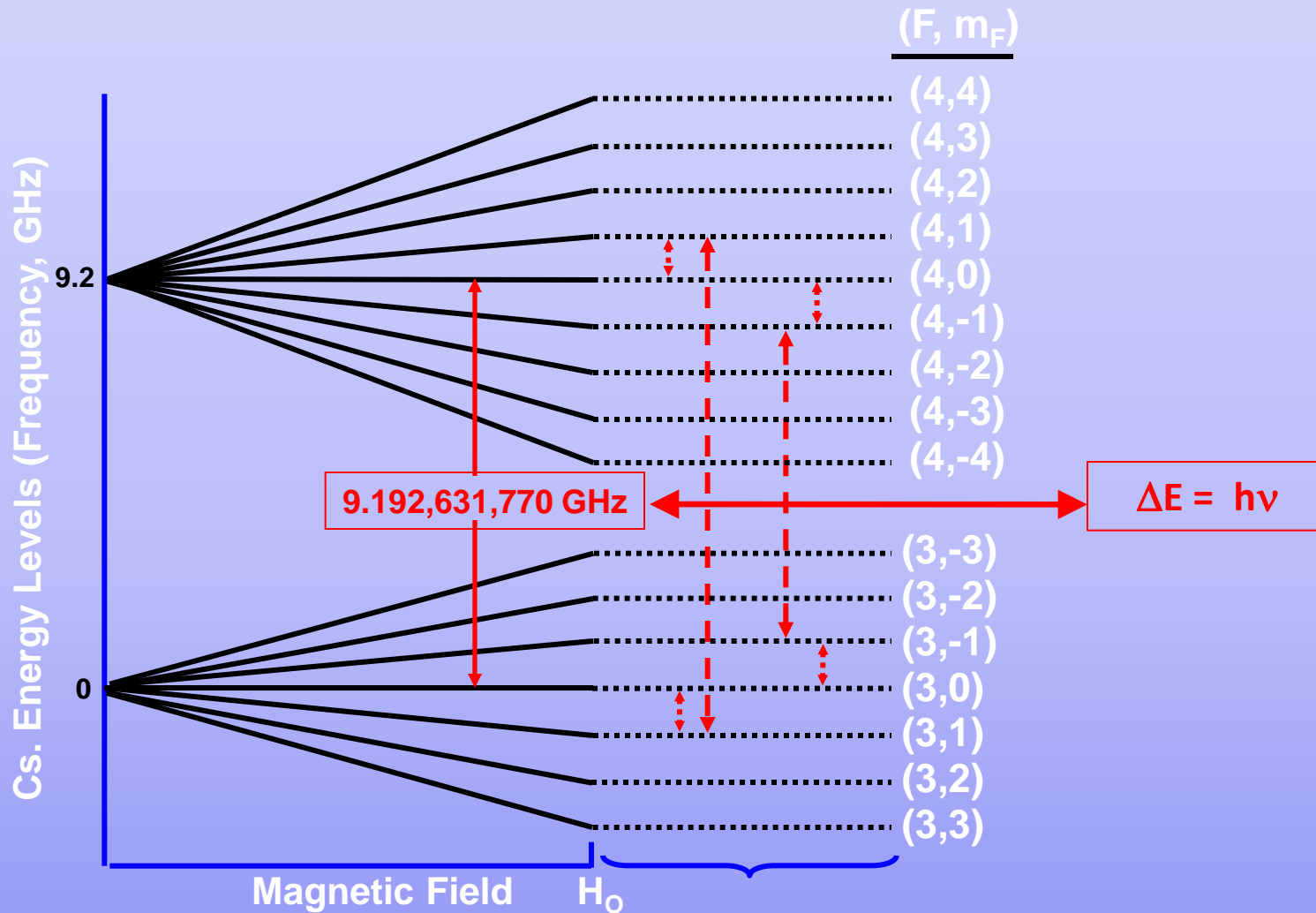
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Primary Sources for Time and Frequency

- **Atomic Clocks**
- **Time and Frequency Transfer**
- **GNSS**
- **Conclusions**
- **Extra Slides**

Atomic Frequency Standards: Produce **Frequency** Locked to an Atomic Transition

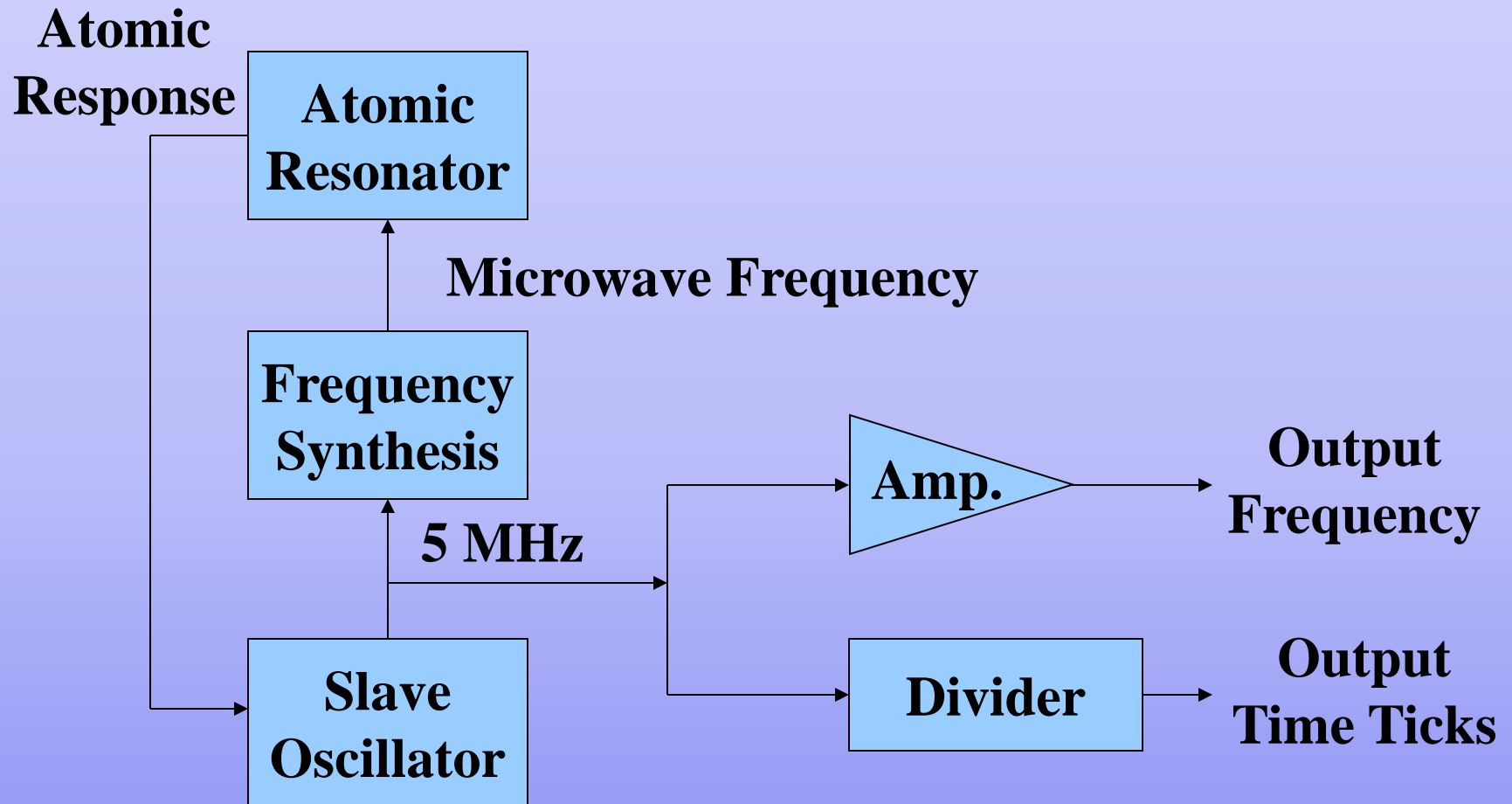


Basic Passive Atomic Clock

1. Obtain atoms to measure
2. Depopulate one hyperfine level
3. Radiate the state-selected sample with frequency ν
4. Measure how many atoms change state
5. Correct ν to maximize measured atoms in changed state

Block Diagram of Atomic Clock

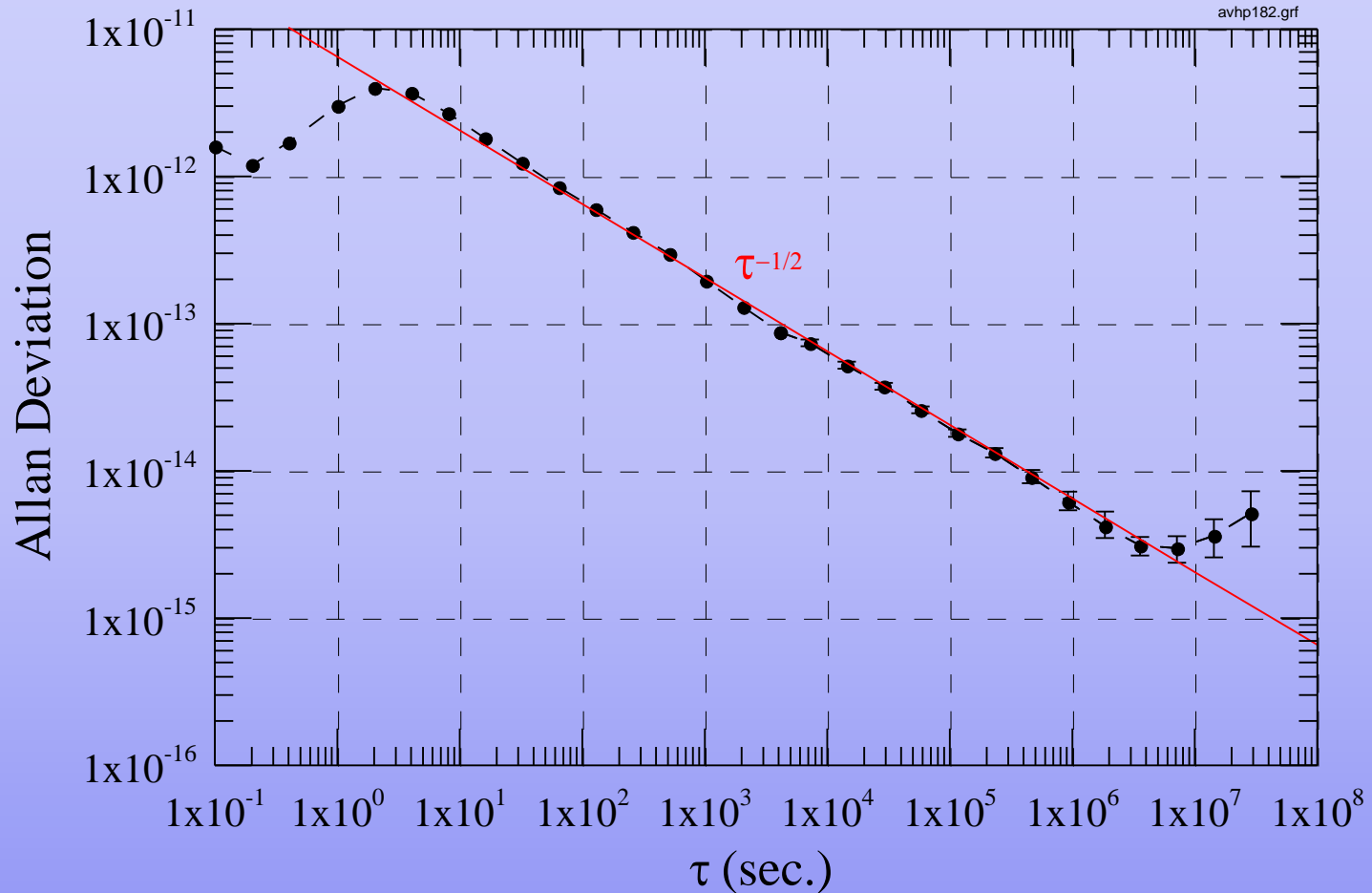
Passive Standard



Types of Atomic Clocks

- Cesium thermal beam standard
 - Best long-term frequency stability
- Rubidium cell standard
 - Small size, low cost
- Hydrogen maser
 - Best stability at 1 to 10 days (short-term stability)
 - Expensive several \$100K
- Chip Scale Atomic Clock (CSAC)
 - Very small size, low power

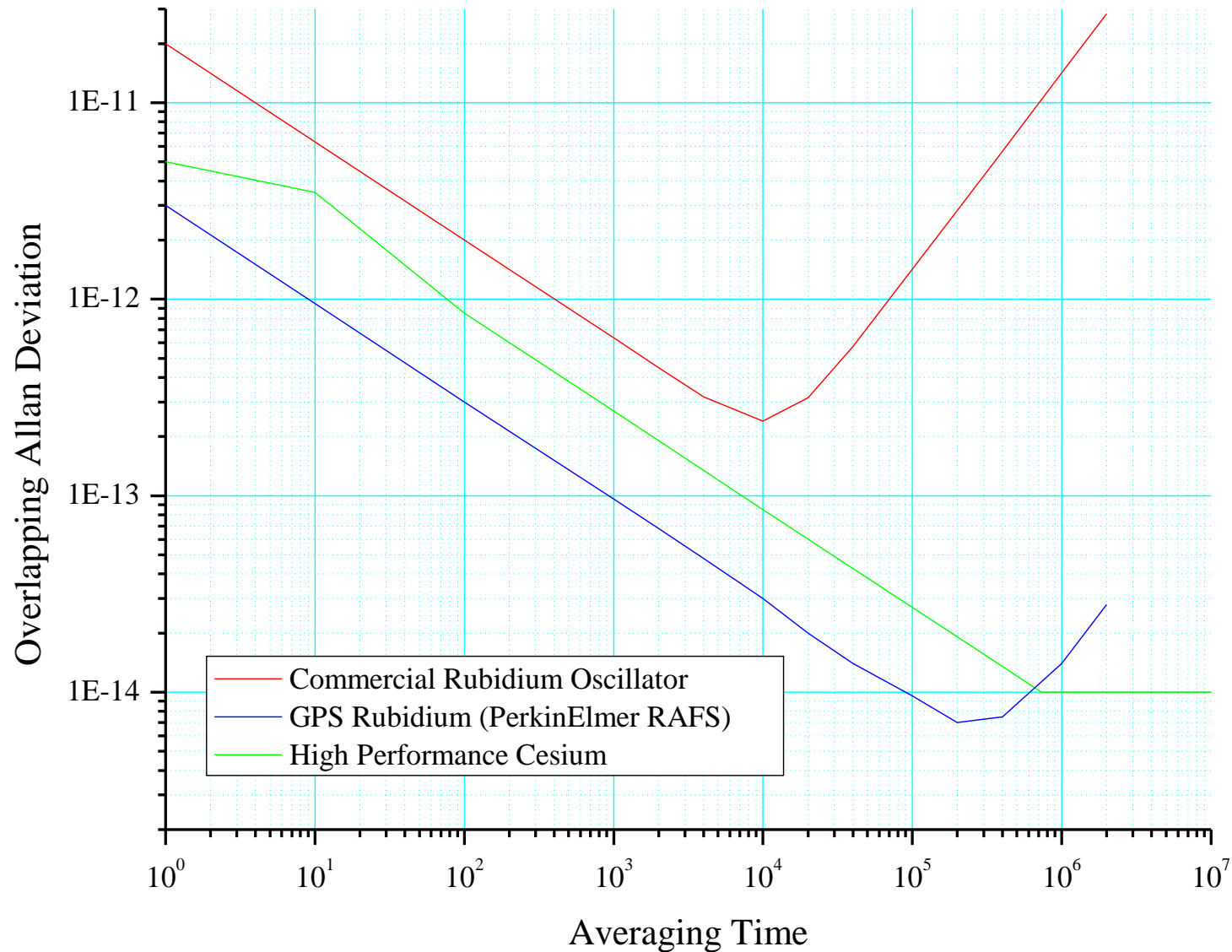
Frequency Stability of a Cesium Standard (No frequency drift removed)



Rubidium Standard

- Two major differences from a cesium standard
 1. Cell standard (doesn't use up rubidium)
 2. Optically pumped (no state selection magnets)
- Used where low cost and small size are important

Frequency Stability of a Rubidium Standard



Something New!

- Chip Scale Atomic Clock (CSAC)
 1. Cesium cell standard
 2. Coherent Population Trapping (CPT)
- Very small size and low power consumption, but better performance than a quartz oscillator

Oscillator Comparison

Technology	Intrinsic Accuracy	Stability (1s)	Stability (floor)	Aging (/day) initial to ultimate	Applications
Cheap Quartz, TCXO	10^{-6}	$\sim 10^{-11}$	$\sim 10^{-11}$	10^{-7} to 10^{-8}	Wristwatch, computer, cell phone, household clock/appliance,...
Hi-quality Quartz, OCXO	10^{-8}	$\sim 10^{-12}$	$\sim 10^{-12}$	10^{-9} to 10^{-11}	Network sync, test equipment, radar, comms, nav,...
Rb Oscillator	$\sim 10^{-9}$	$\sim 10^{-11}$	$\sim 10^{-13}$	10^{-11} to 10^{-13}	Wireless comms infrastructure, lab equipment, GPS, ...
Cesium Beam	$\sim 10^{-13}$	$\sim 10^{-11}$	$\sim 10^{-14}$	nil	Timekeeping, Navigation, GPS, Science, Wireline comms infrastructure,...
Hydrogen Maser	$\sim 10^{-11}$	$\sim 10^{-13}$	$\sim 10^{-15}$	10^{-15} to 10^{-16}	Timekeeping, Radio astronomy, Science,...

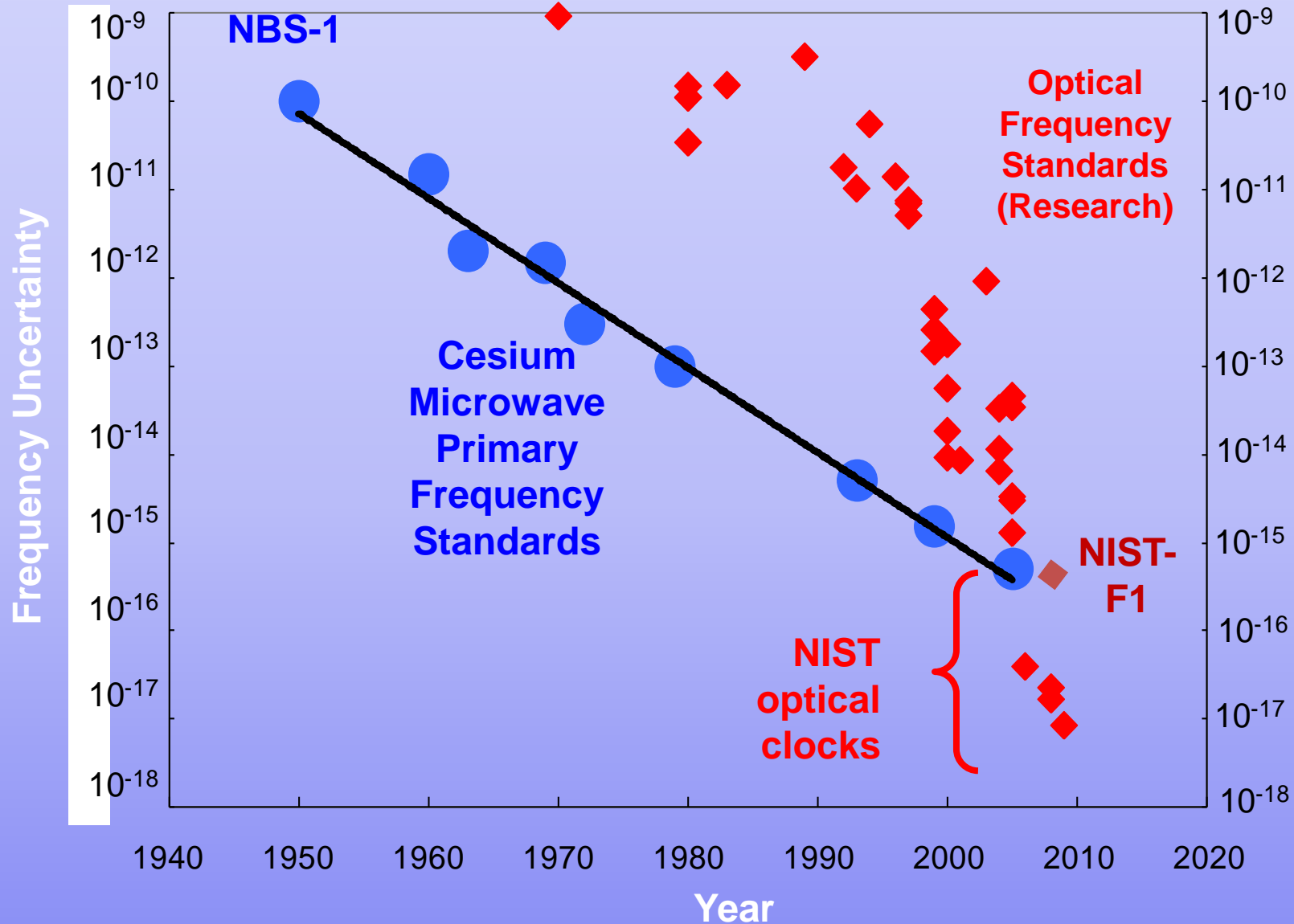
Oscillator Comparison (continued)

Technology	Size	Weight	Power	World Market	Cost
Cheap Quartz, TCXO	$\approx 1 \text{ cm}^3$	$\approx 10 \text{ g}$	$\approx 10 \text{ mW}$	$\approx 10^9\text{s/year}$	$\approx \$1\text{s}$
Hi-quality Quartz, OCXO	$\approx 50 \text{ cm}^3$	$\approx 500 \text{ g}$	$\approx 10 \text{ W}$	$\approx 10\text{Ks/year}$	$\approx \$100\text{s}$
Rb Oscillator	$\approx 200 \text{ cm}^3$	$\approx 500 \text{ g}$	$\approx 10 \text{ W}$	$\approx 10\text{Ks/year}$	$\approx \$1000\text{s}$
Cesium Beam	$\approx 30,000 \text{ cm}^3$	$\approx 20 \text{ kg}$	$\approx 50 \text{ W}$	$\approx 100\text{s/year}$	$\approx \$10\text{Ks}$
Hydrogen Maser	$\approx 1 \text{ m}^3$	$\approx 200 \text{ kg}$	$\approx 100 \text{ W}$	$\approx 10\text{s/year}$	$\approx \$100\text{Ks}$

Conclusions: Atomic Standards

- **Rubidium, cesium, and hydrogen atomic frequency standards share a common theme: the stabilization of an electronic (quartz) oscillator with respect to an atomic resonance.**
- **Although the use of atoms brings with it new quantum mechanical problems, the resulting long-term stability is unmatched by traditional classical oscillators.**

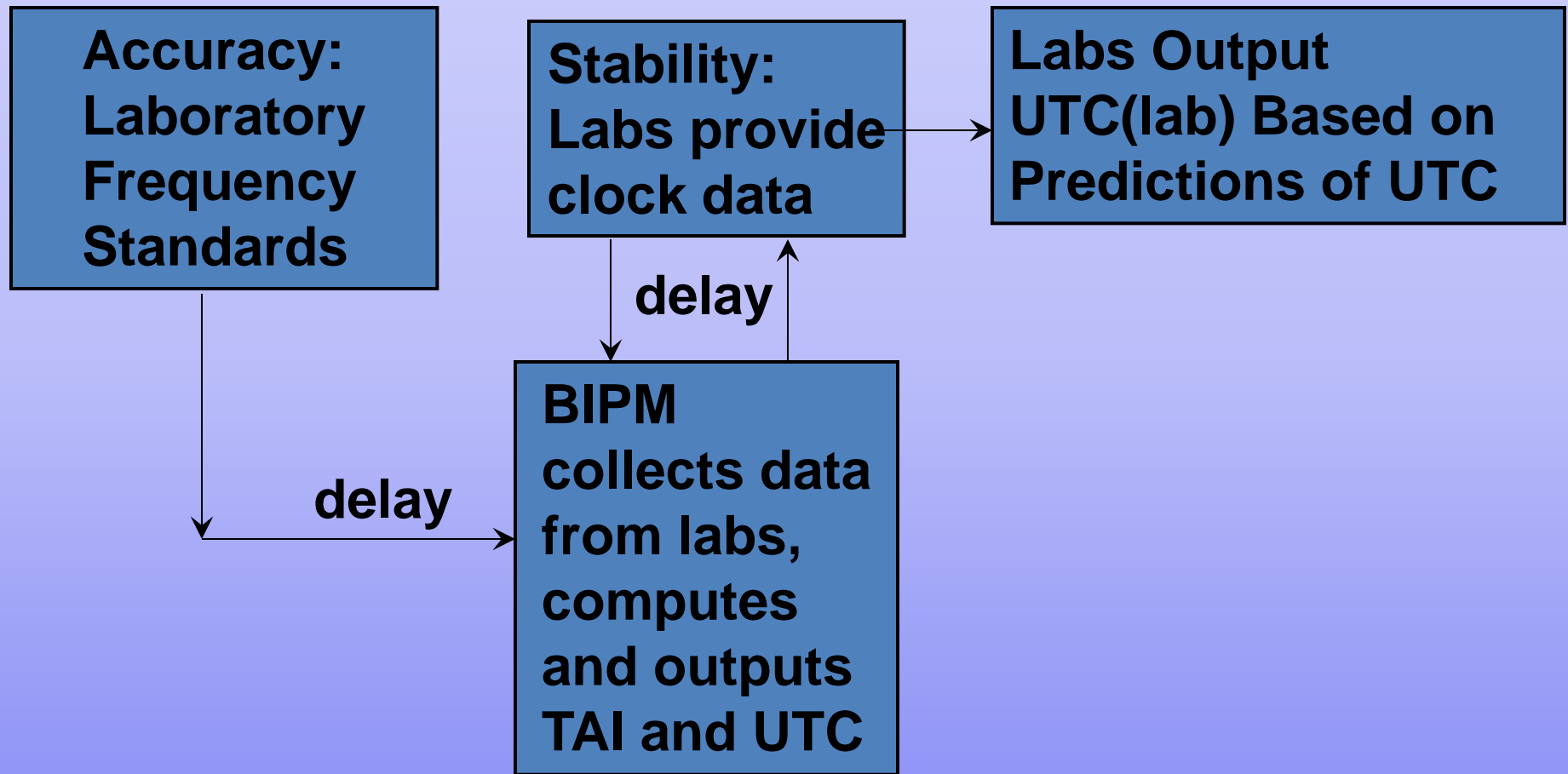
Frequency Accuracy: History of NIST Primary Frequency Standards



The Generation of UTC: Time Accuracy

Any Real Time UTC is only a Prediction,

A PLL with a one-month delay



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- **Conclusions**
- **Extra Slides**

Time and Frequency Transfer: How to Deliver a Timing Reference

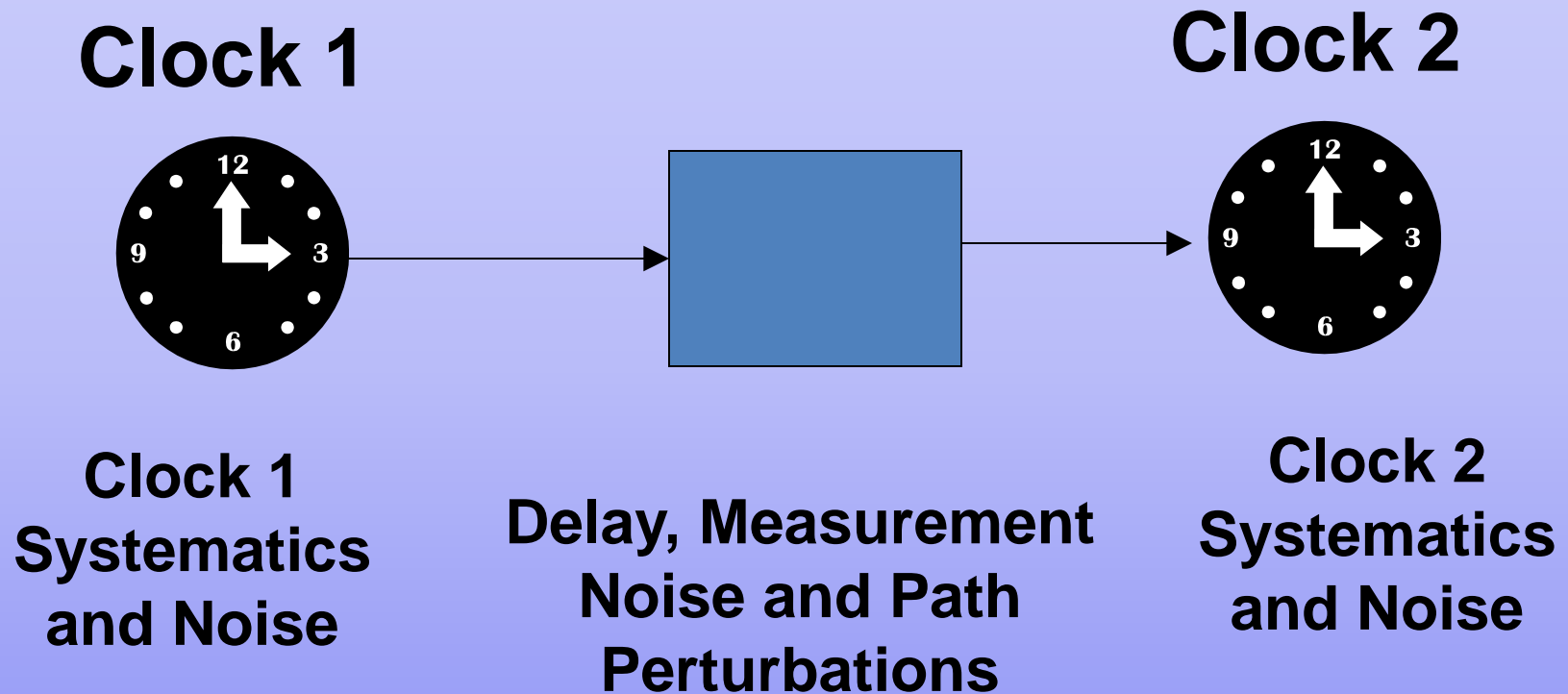
- Time Transfer **Accuracy** Requires Calibrating Delays



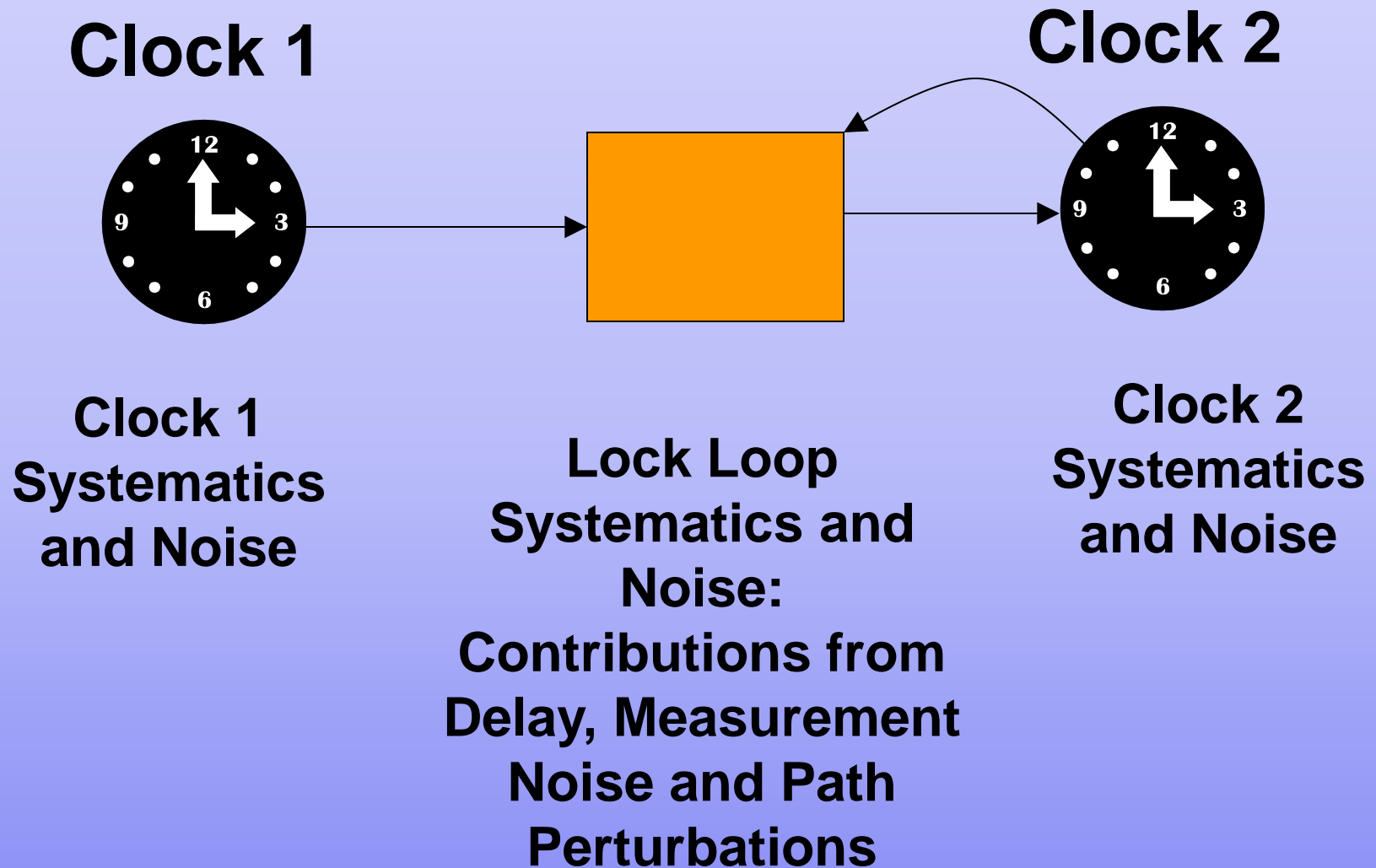
- Imagine writing a letter: “It is now 2 PM— set your watch”
- Seal it in an envelope and drop it in a mail box
- Only useful if you know how long it took to get to you
- Now suppose you timestamped when you sealed the letter and the receiving person timestamped when he got it...

- Time **Stability** = Frequency Accuracy

One-Way Dissemination or Comparison System

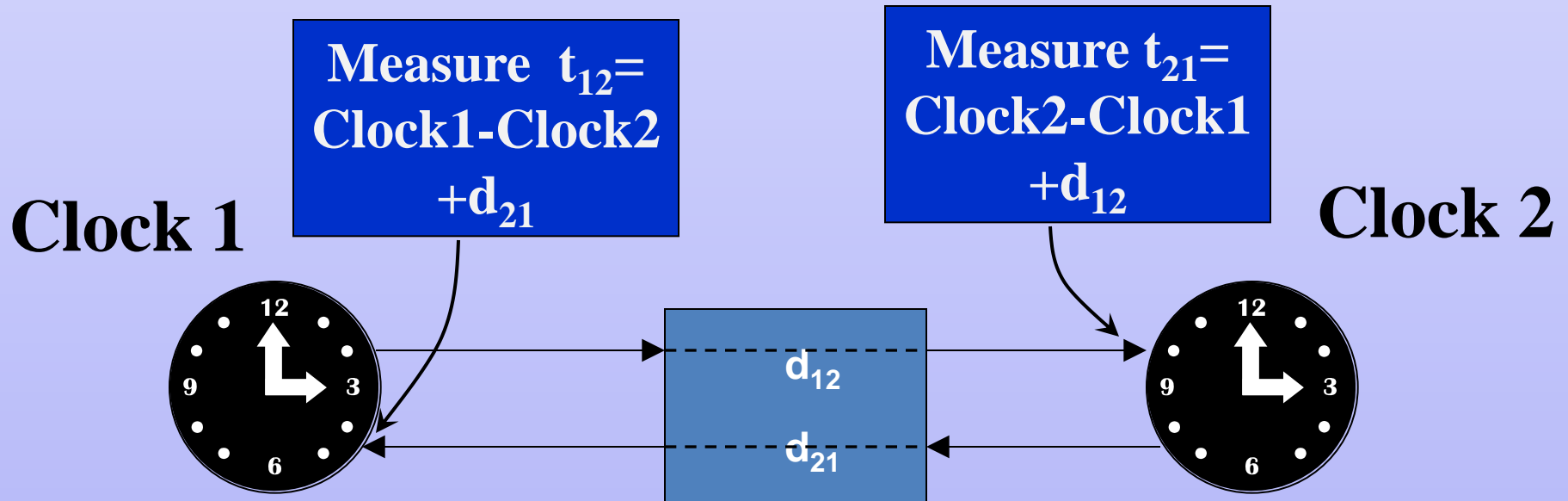


Clock Hierarchies



Two -Way Comparison System

(e.g. IEEE1588 – PTP)



Clock 1
Systematics
and Noise

Measurement Noise
and Path Perturbations
Largely Reciprocal:

$$d_{21} = d_{12}$$

Clock 2
Systematics
and Noise

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The Family of Global Navigation Systems

GPS US (24+, Now 30)	Galileo EU (27, Now 3?)	GLONASS Russia (24, Now 24)	Beidou/Compass China (35, Now 14?)
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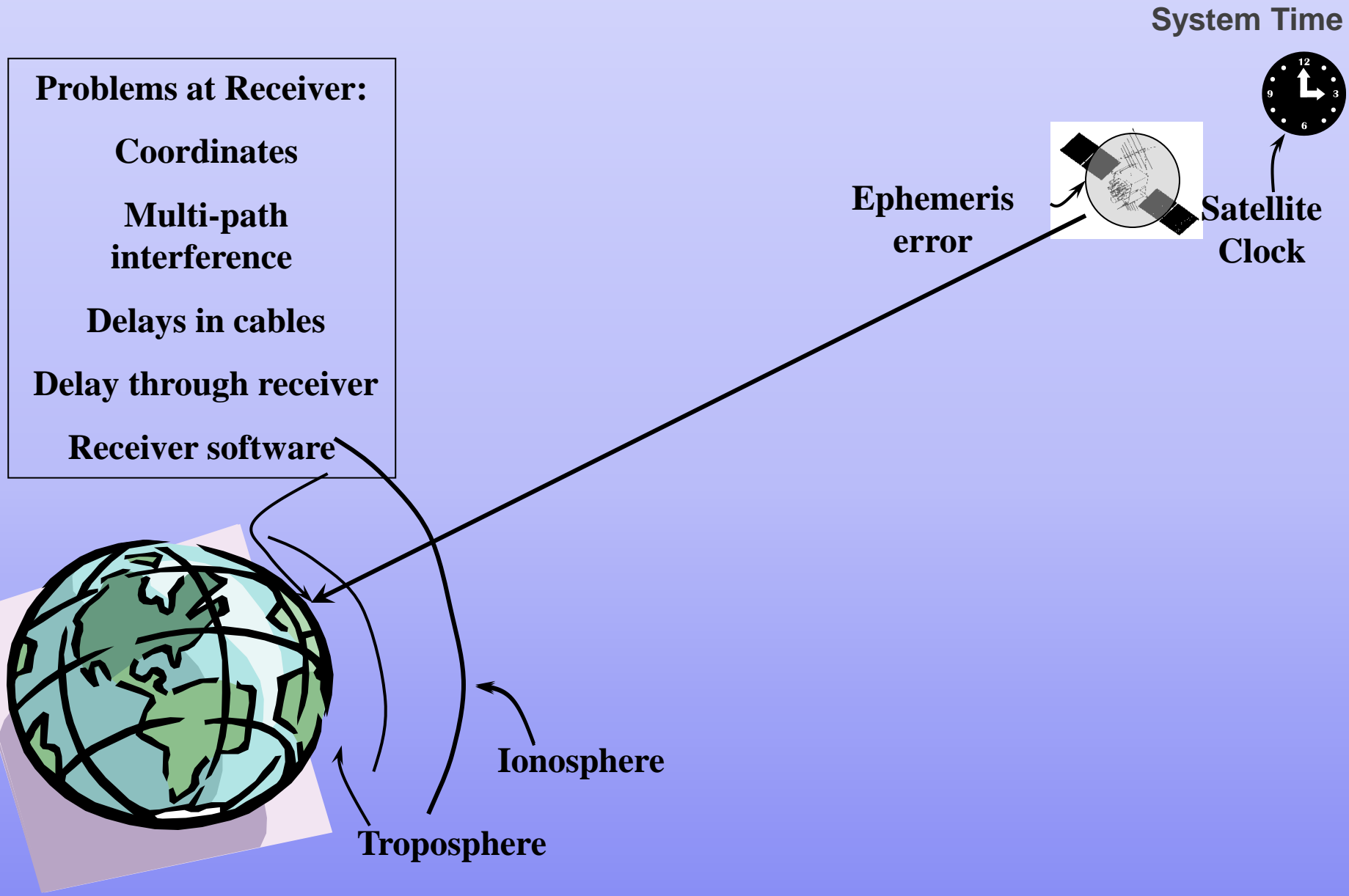
Two Messages About GNSS

1. GNSS are extremely useful
 1. Constellations are growing
 2. Provide reliable, extremely accurate real-time UTC time and frequency for mostly free
 3. Excellent navigation
 4. A global > \$100B industry
2. GNSS signals are dangerously vulnerable to both accidental and intentional interference

GNSS Systems: General Properties

- Position, Navigation, Timing (PNT)
- Four + synchronized timing signals from known locations in space required for navigation
- Two + frequencies measure ionosphere
- Control, Space, User Segments
- Open and Restricted Services
- All signals are weak and clustered in the spectrum
 - Allows interoperability
 - But also makes it is relatively easy to jam GNSS and spoof

Time from GNSS: Noise Sources

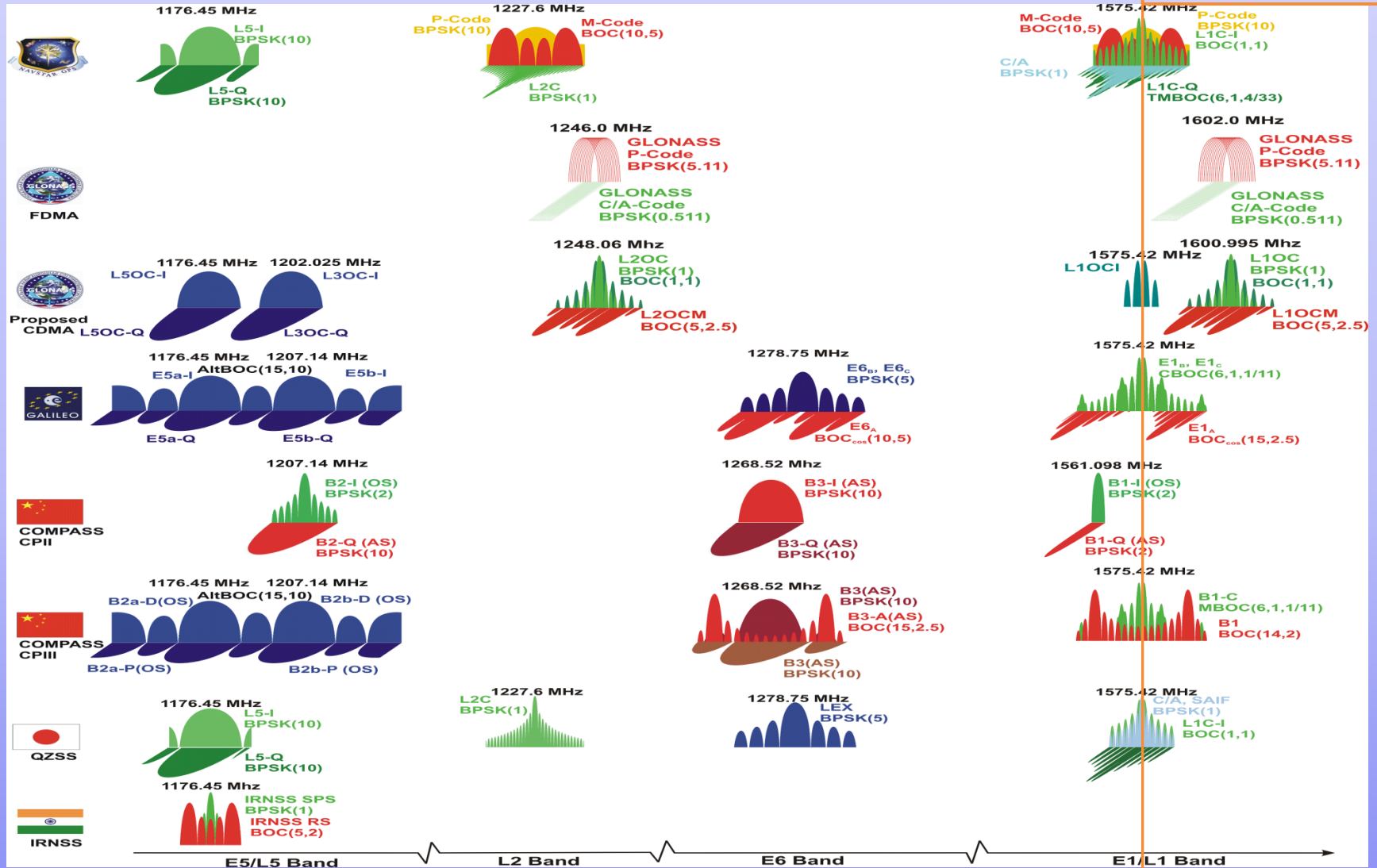


Time From GNSS

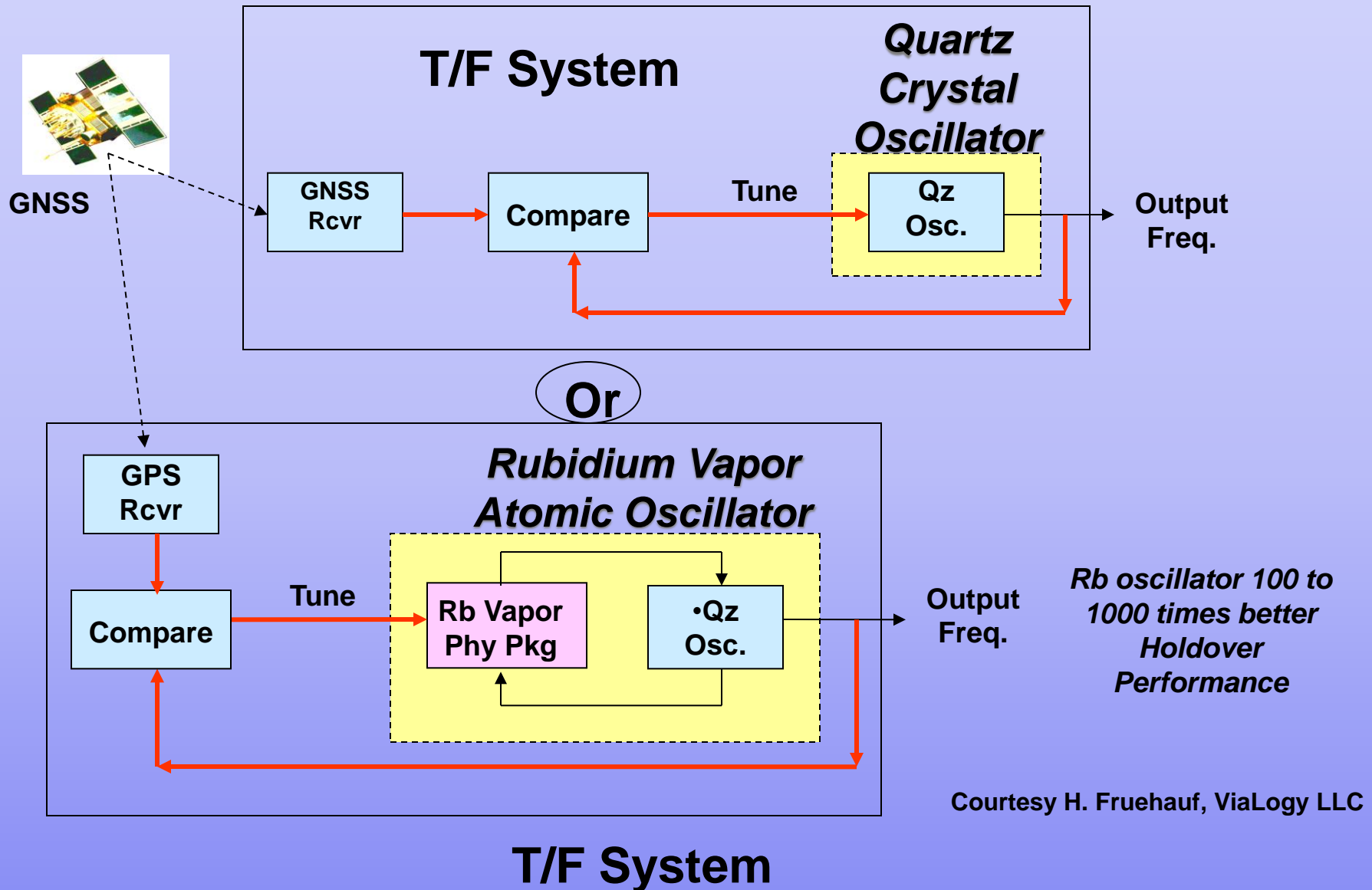
- Clocks on Satellite Vehicles (SVs) are free-running
 - Data provides the offset in Time and Frequency
 - System time is offset from UTC
- The positions of the satellite and receiver are needed for the delay
- SV Clocks and positions are *predicted* and uploaded, for GPS about once per day

Spectra of GNSS's

Primary
Commercial
Signal



GNSS-aided Time and Frequency Systems



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Conclusions

- Atomic clocks are accurate and/or stable by design
 - Cs. can be a primary frequency standard
 - Others can be very stable
- Time transfer requires calibration of the delay
 - Two-way cancels the delay if it is symmetric
 - GNSS measures the delay
 - Frequency transfer only requires stable delay
- GNSSs are very accurate both for time and frequency, many signals free for use, and are very reliable
 - Perhaps their greatest advantage and disadvantage!
 - Signals are subject to interference

Thanks for your attention!

Extra slides follow

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Clock Stability

Clock (in)stability is given by:

$$\sigma \approx \frac{\delta f}{f} \propto \frac{1}{Q(S/N)} = \frac{1}{(\omega / \Delta\omega)(S/N)}$$

Atomic Line Q

Signal to Noise

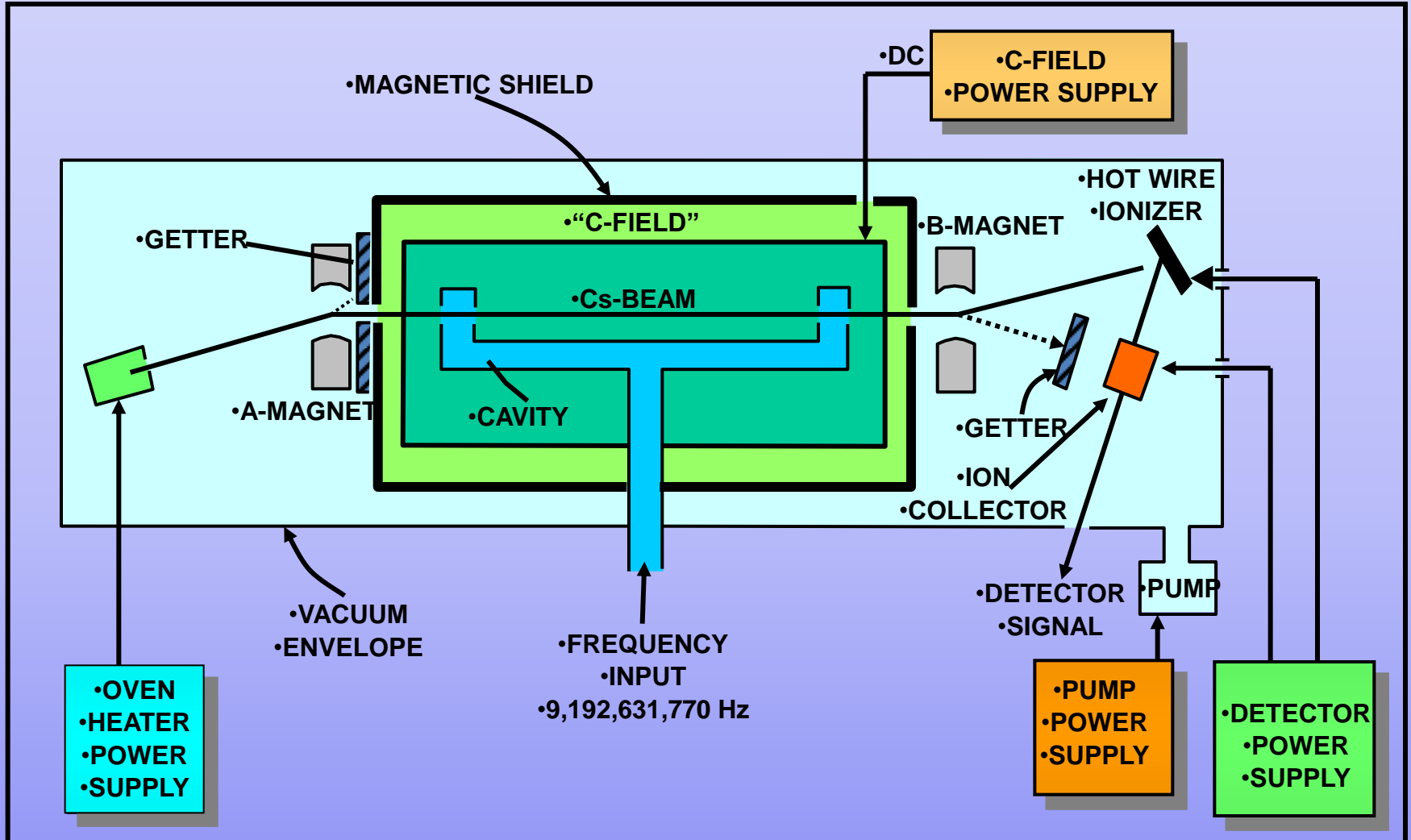
Clock stability can be improved by:

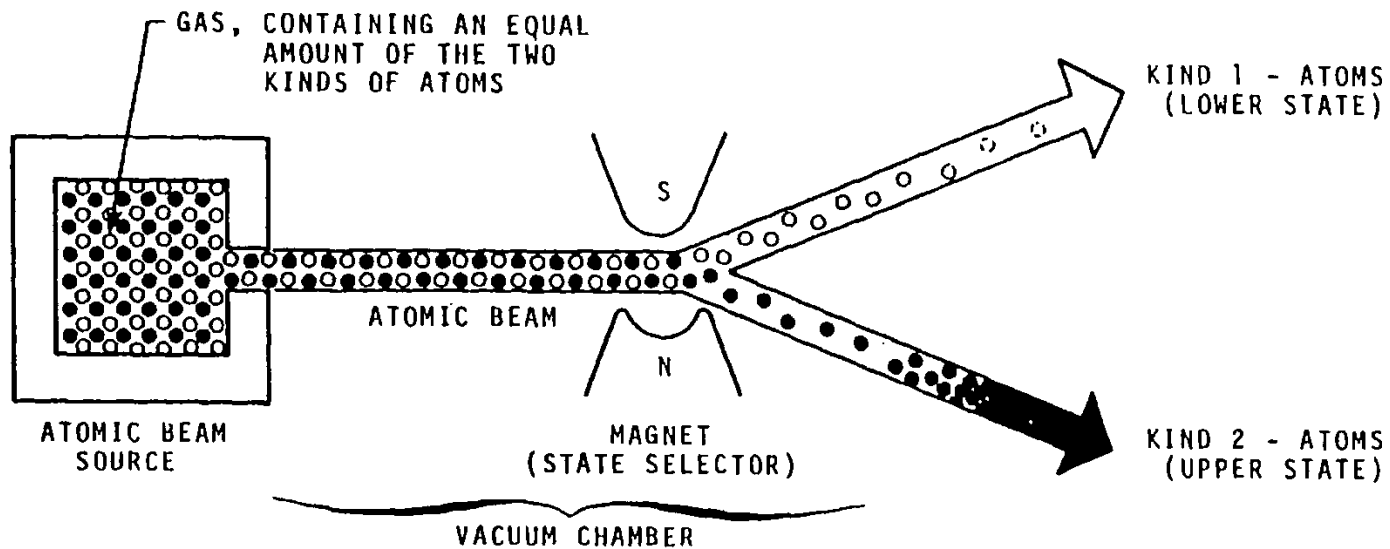
Increase Ramsey (observation) times (decrease $\Delta\omega = 1/T_{\text{Ramsey}}$)

Improve the S/N (more atoms!)

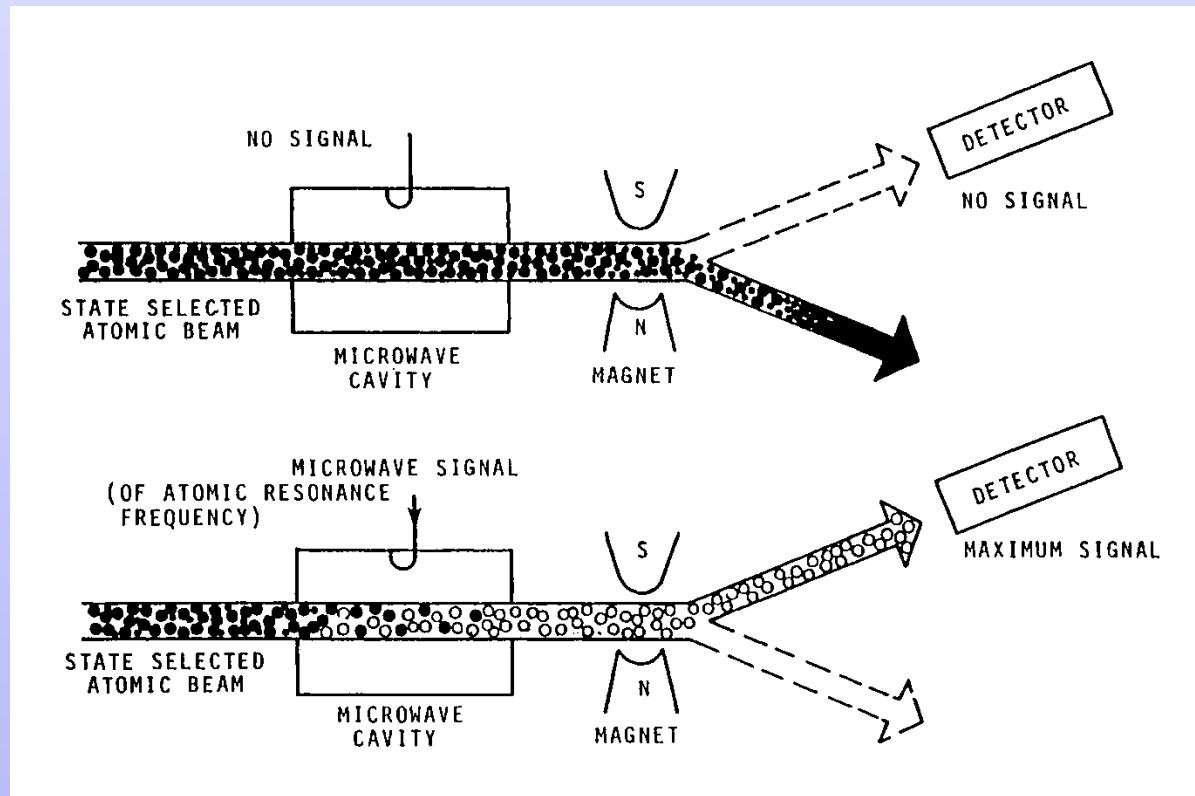
Increase the frequency of the clock transition (optical?)

Cesium Standard



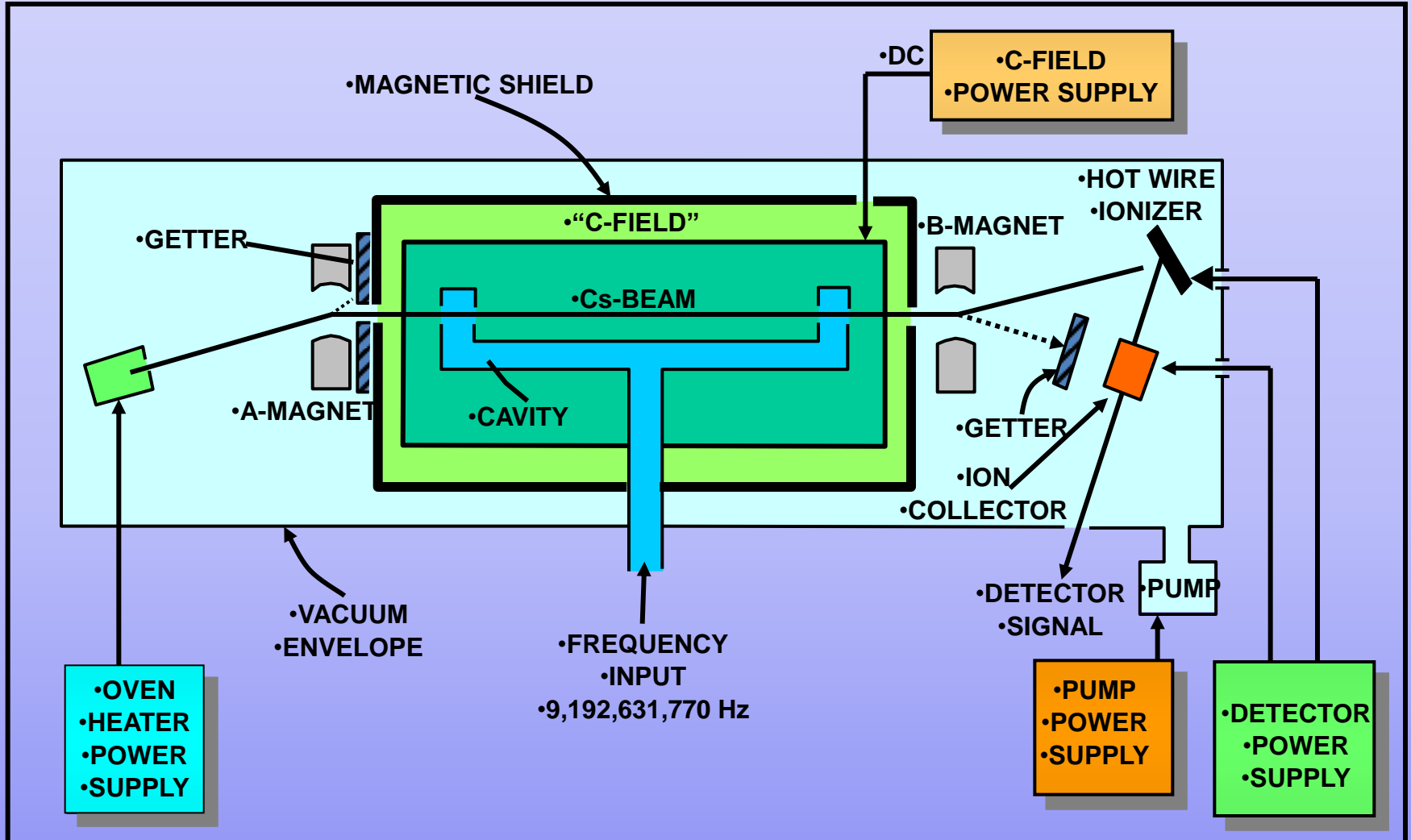


- Atoms come from an oven in a beam
-
- A magnet is used to deflect the atoms in different
 - hyper-fine states



- Atoms pass through a Ramsey cavity in a magnetic field to be exposed to microwaves at frequency $\nu = 9.193 \text{ GHz}$
- A second magnet selects atoms which have made the transition
- The number of detected atoms is used to tune the frequency

Cesium Standard



Commercial Cesium Standards



•Laboratory/Timekeeping

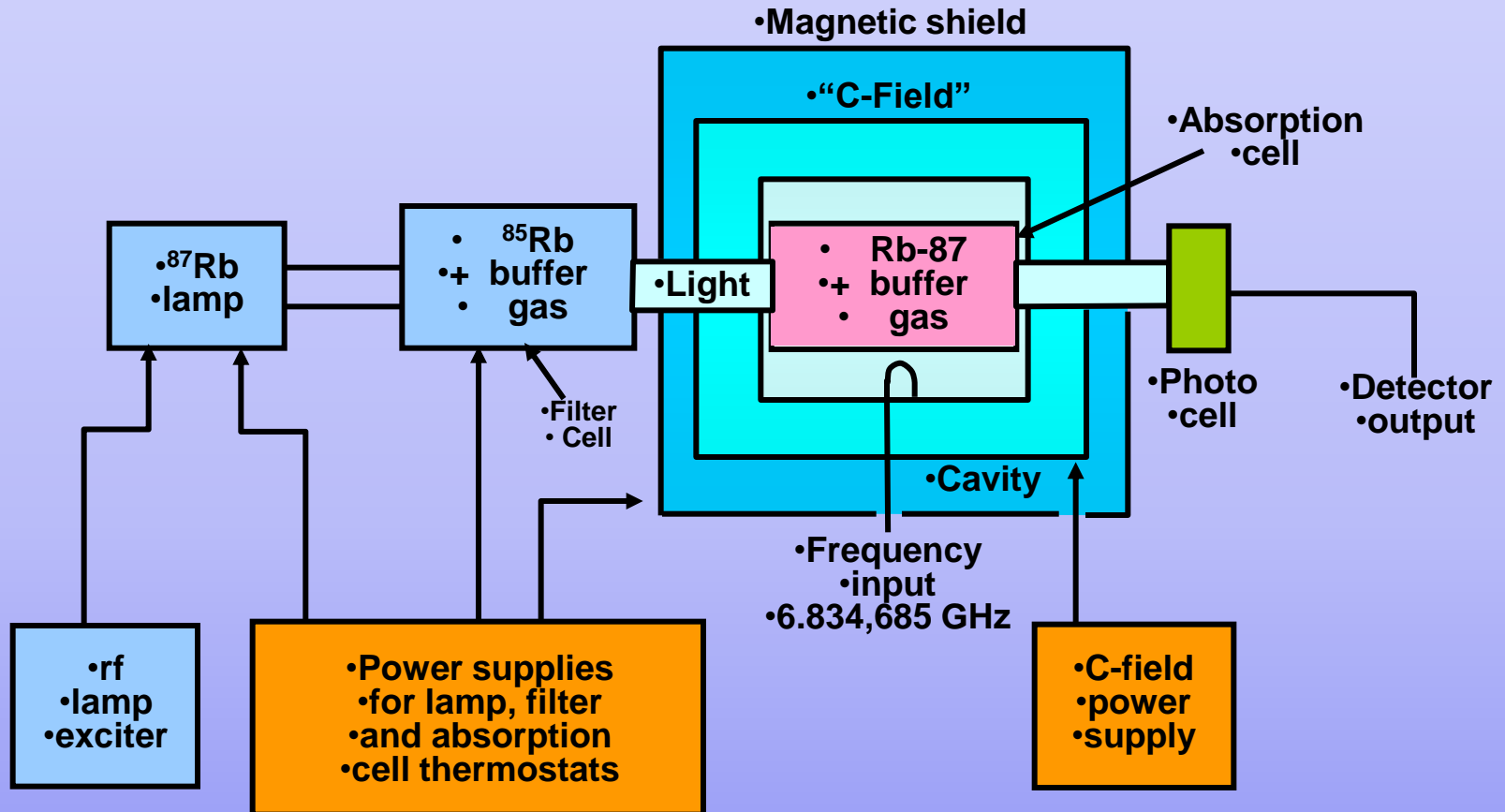


•Telecom



•Space/GPS

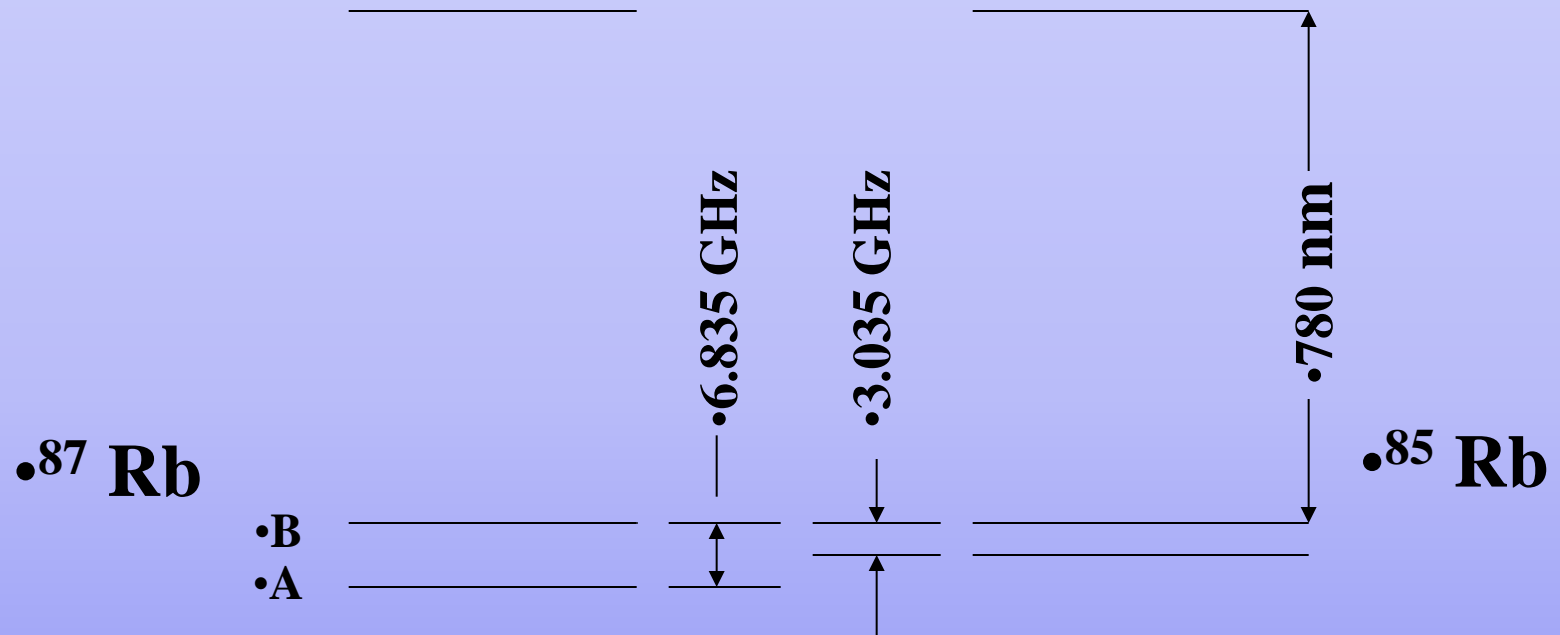
Rubidium Standard

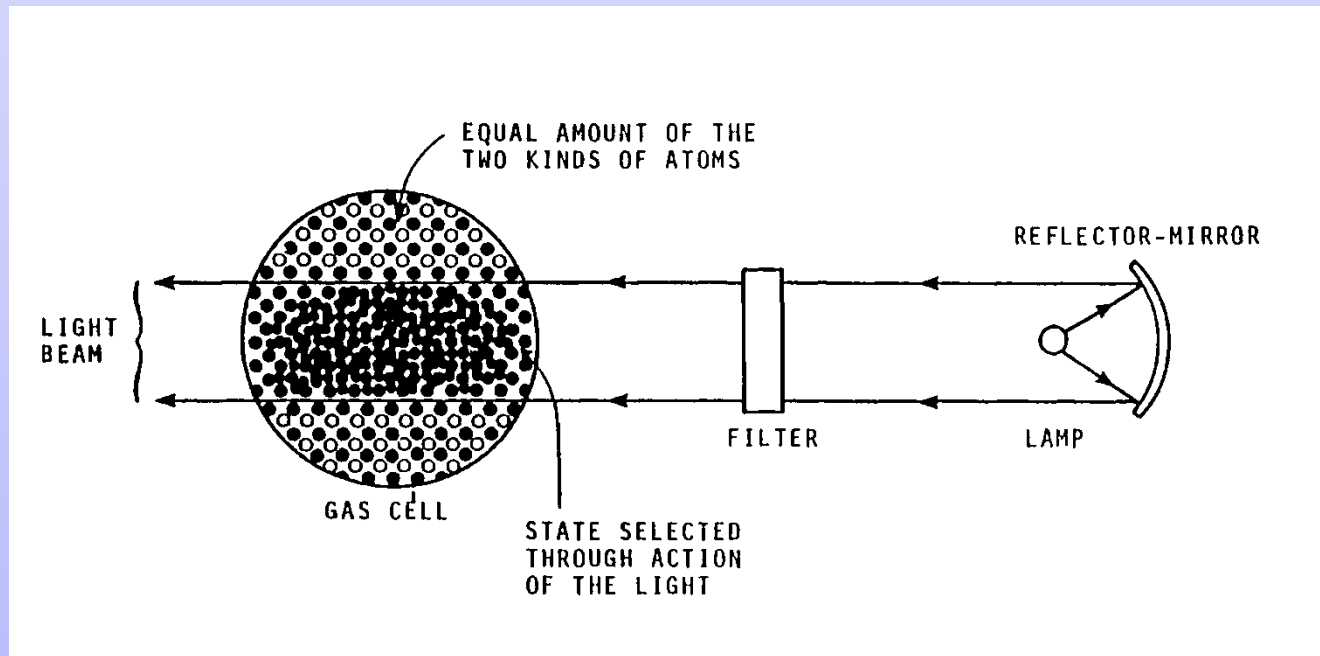


•Adapted from figure by John Vig

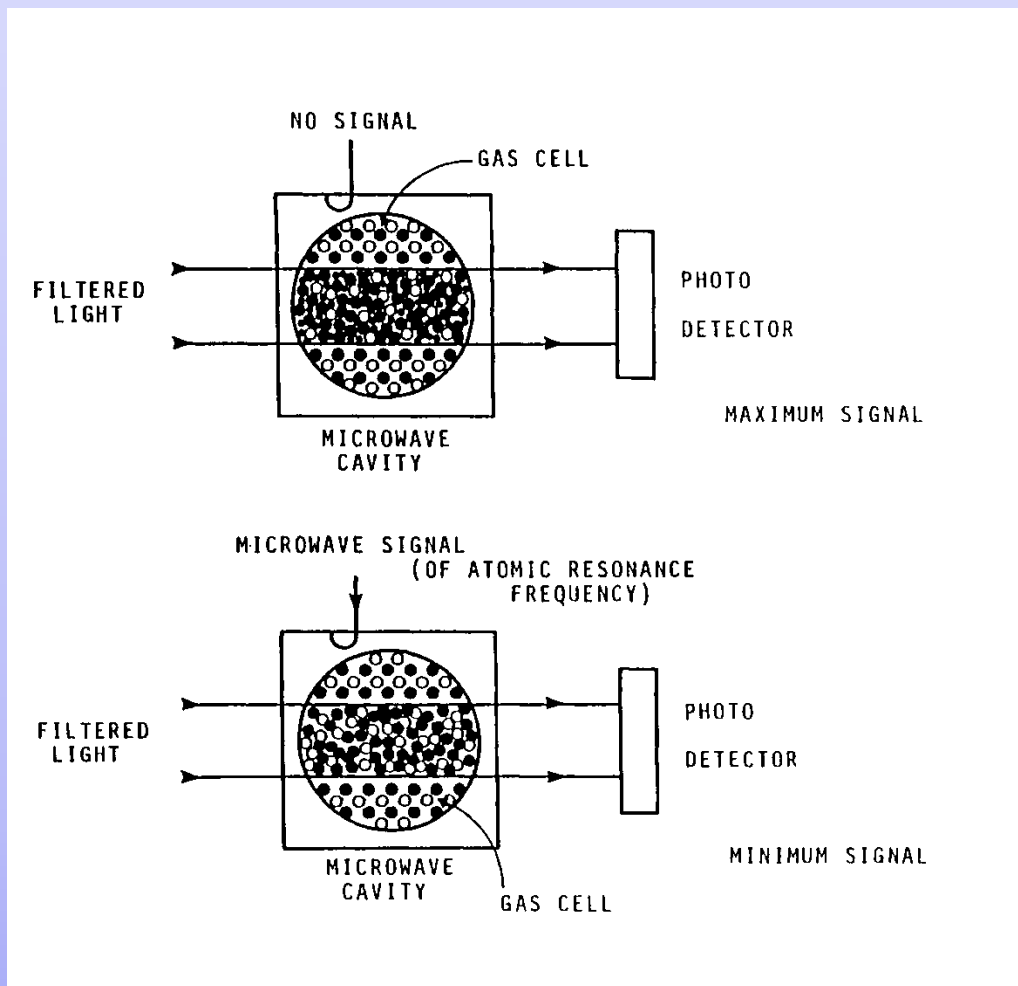
Optical Microwave Double Resonance

Simplified Rb energy level diagram



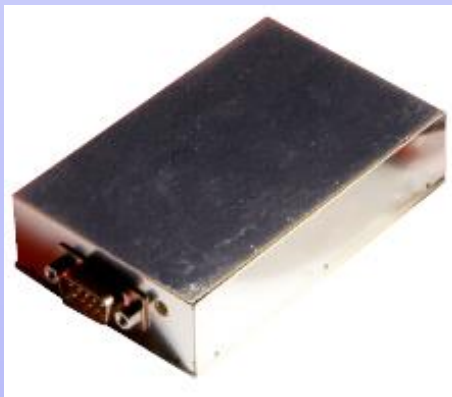


- **Optical pumping is used to deplete one hyper-fine level**
- **Light tuned to the transition frequency from “A” to the**
 - **unstable excited state puts all of the atoms in the**
 - **hyper-fine state “B”**



- Microwaves at $\nu = 6.835$ GHz stimulate the transition from “B” to “A”
- The absorption of light is measured
- The frequency ν is tuned to minimize the light coming through the ^{87}Rb cell

Commercial Rubidium Standards



•Quartzlock E10



•Stanford Research PRS10



•Frequency Electronics
• FE-5680A



•Temex SR100



•PerkinElmer GPS RAFS



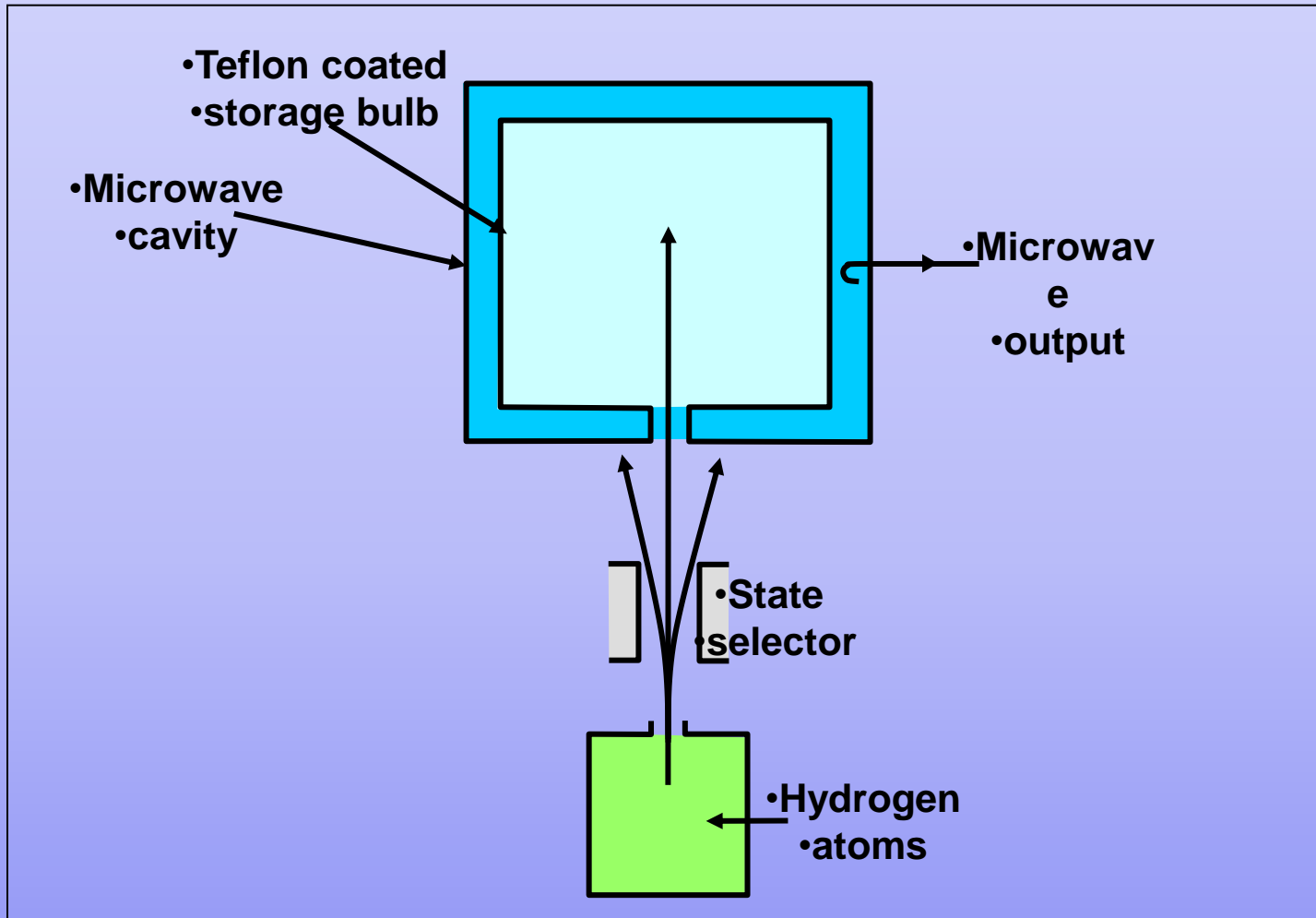
•Symmetricom X72



•Accubeat AR-70A

Hydrogen Maser

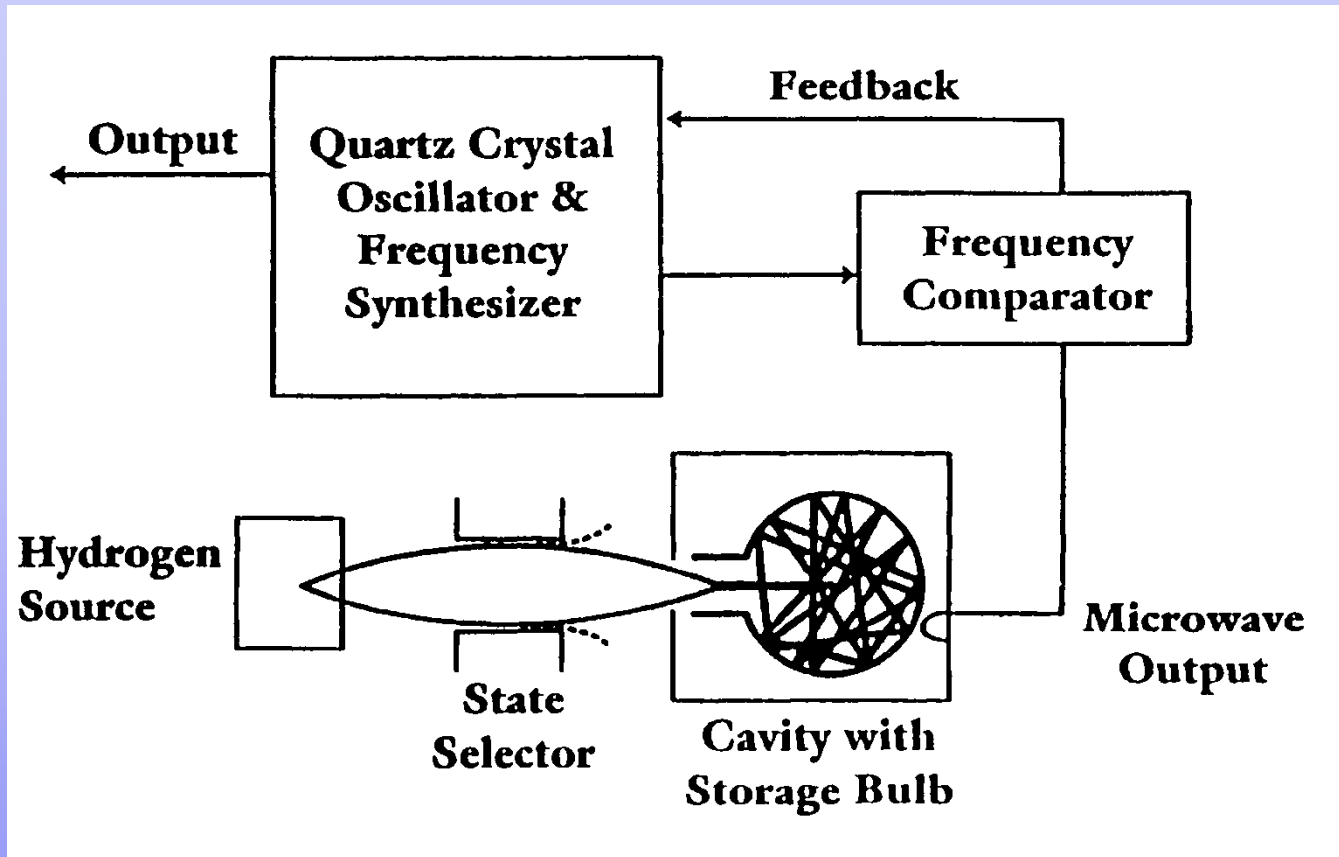
(Active Standard)



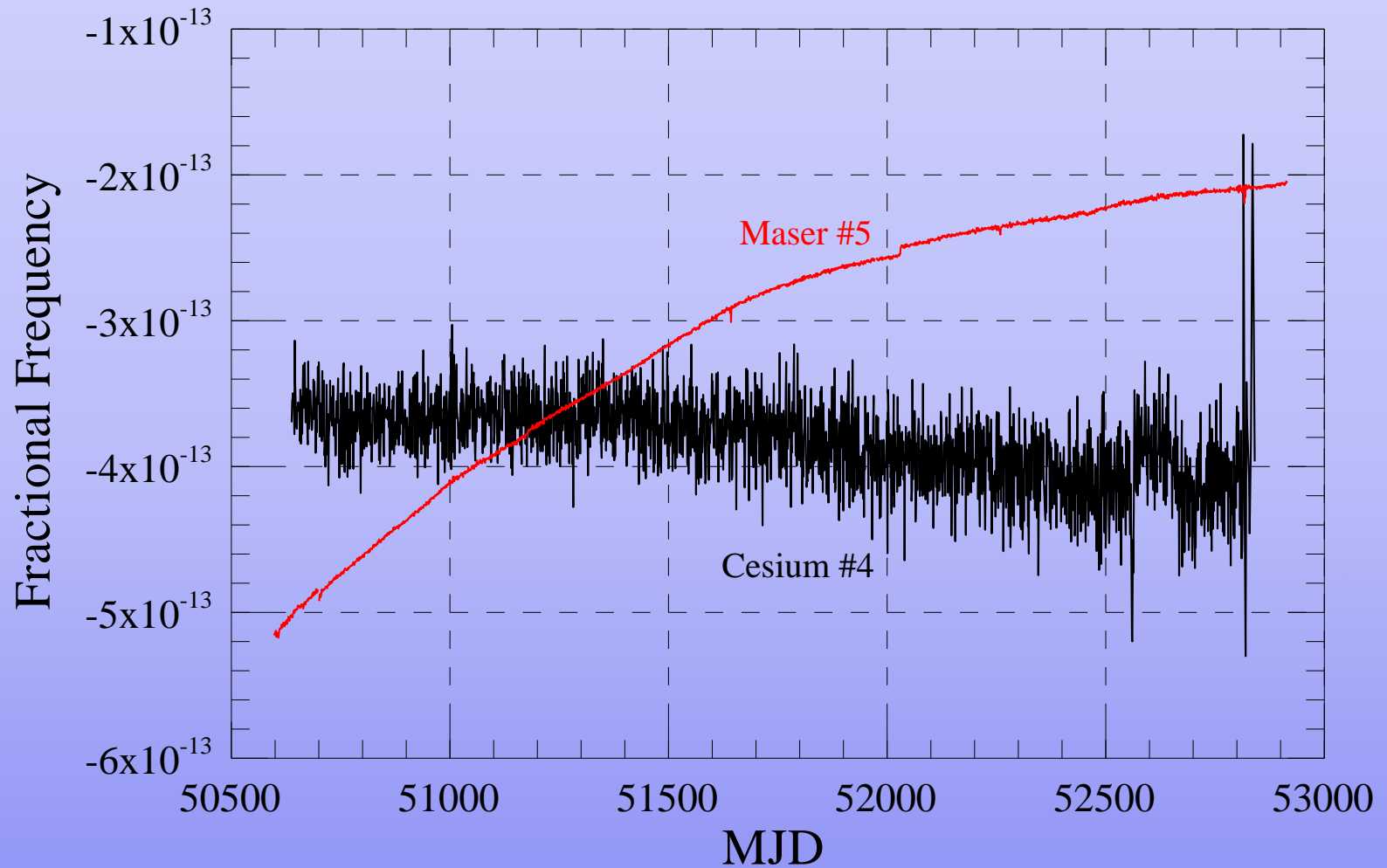
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Hydrogen Maser

(Active Standard)



Frequency Drift of a Commercial Cesium Standard and a Hydrogen Maser



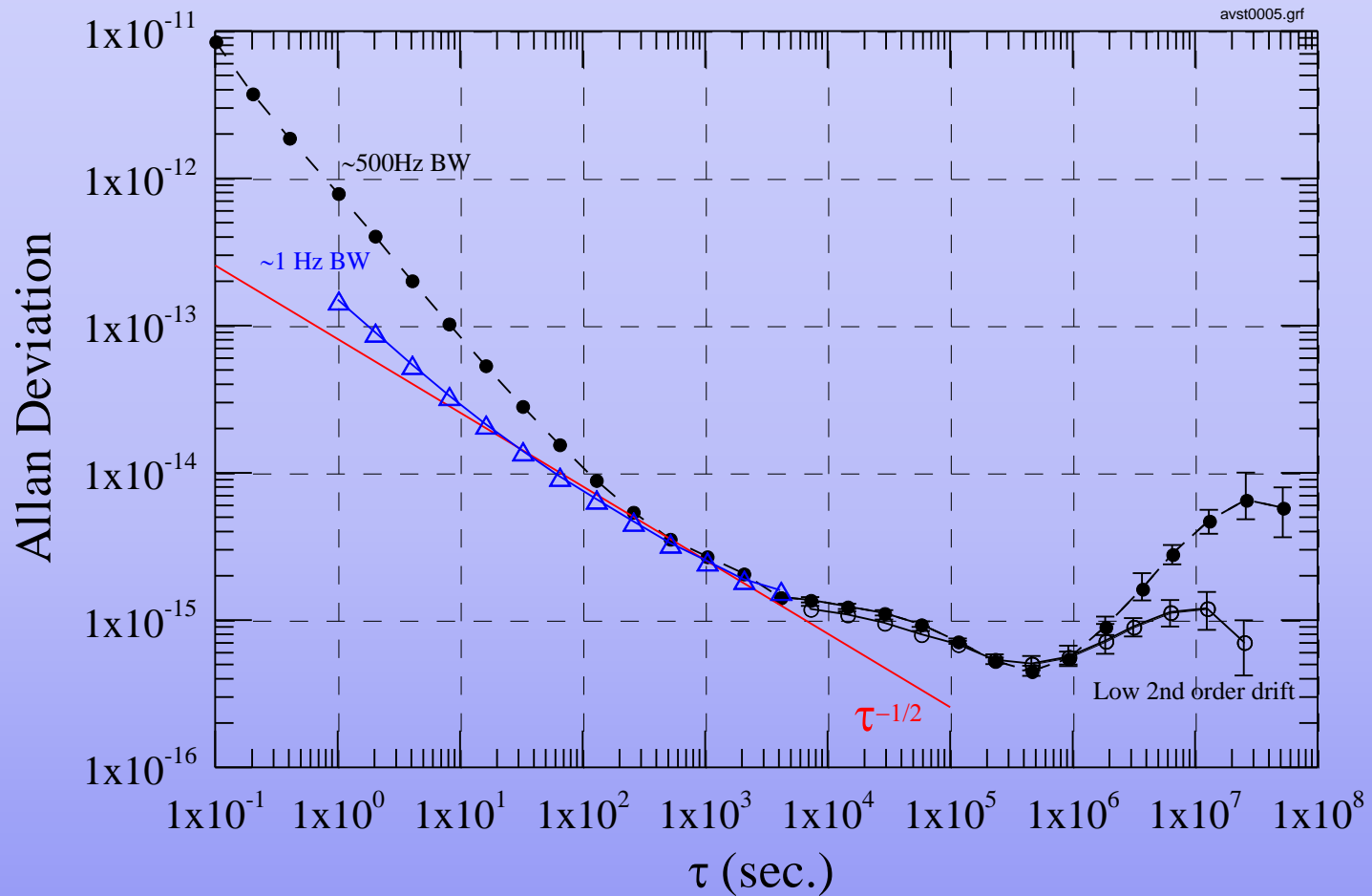
Commercial Active Hydrogen Maser



•Courtesy of Robert Lutwak, Symmetricom

Frequency Stability of a Hydrogen Maser

(Frequency drift removed – 1×10^{-16} /day typical)



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Time and Frequency Transfer: How to Deliver a Timing Reference

- Time Transfer **Accuracy** Requires Calibrating Delays



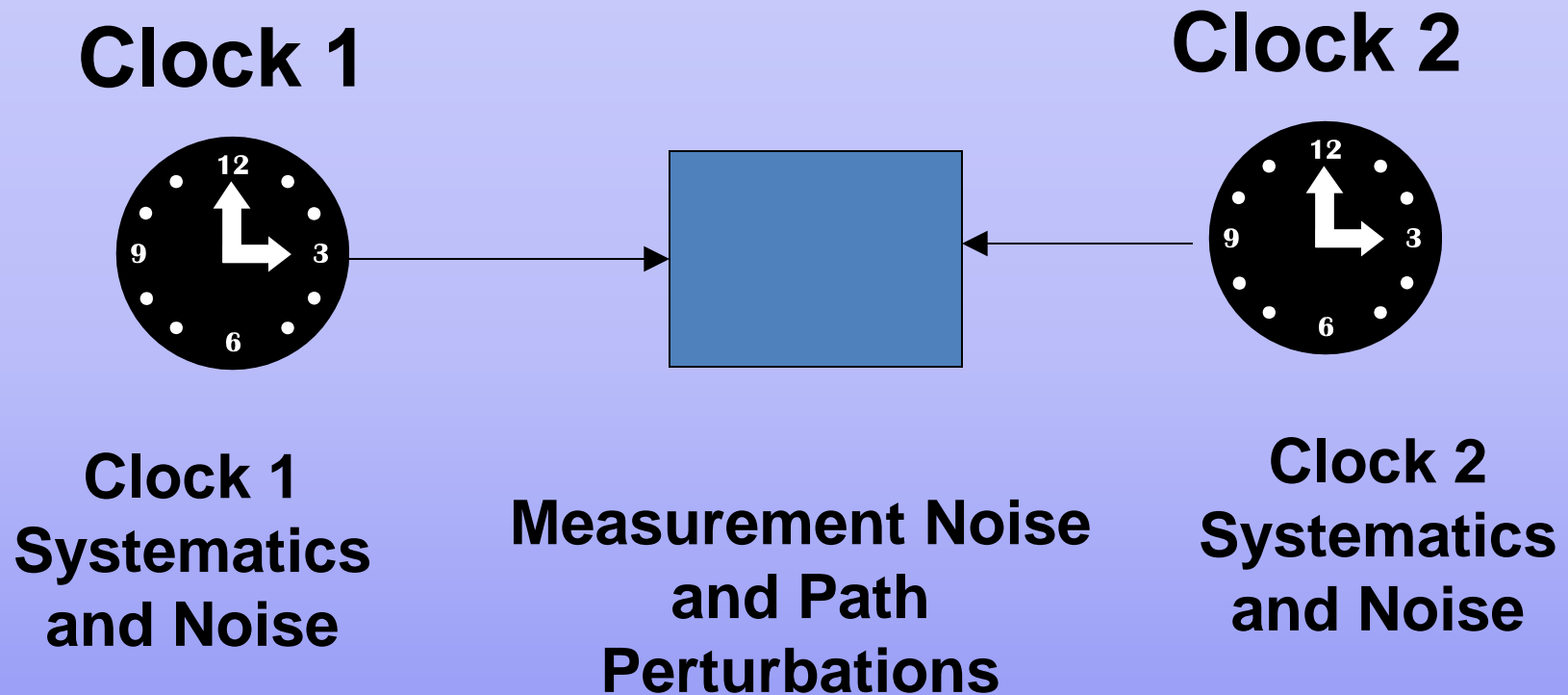
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- Time **Stability** = Frequency Accuracy

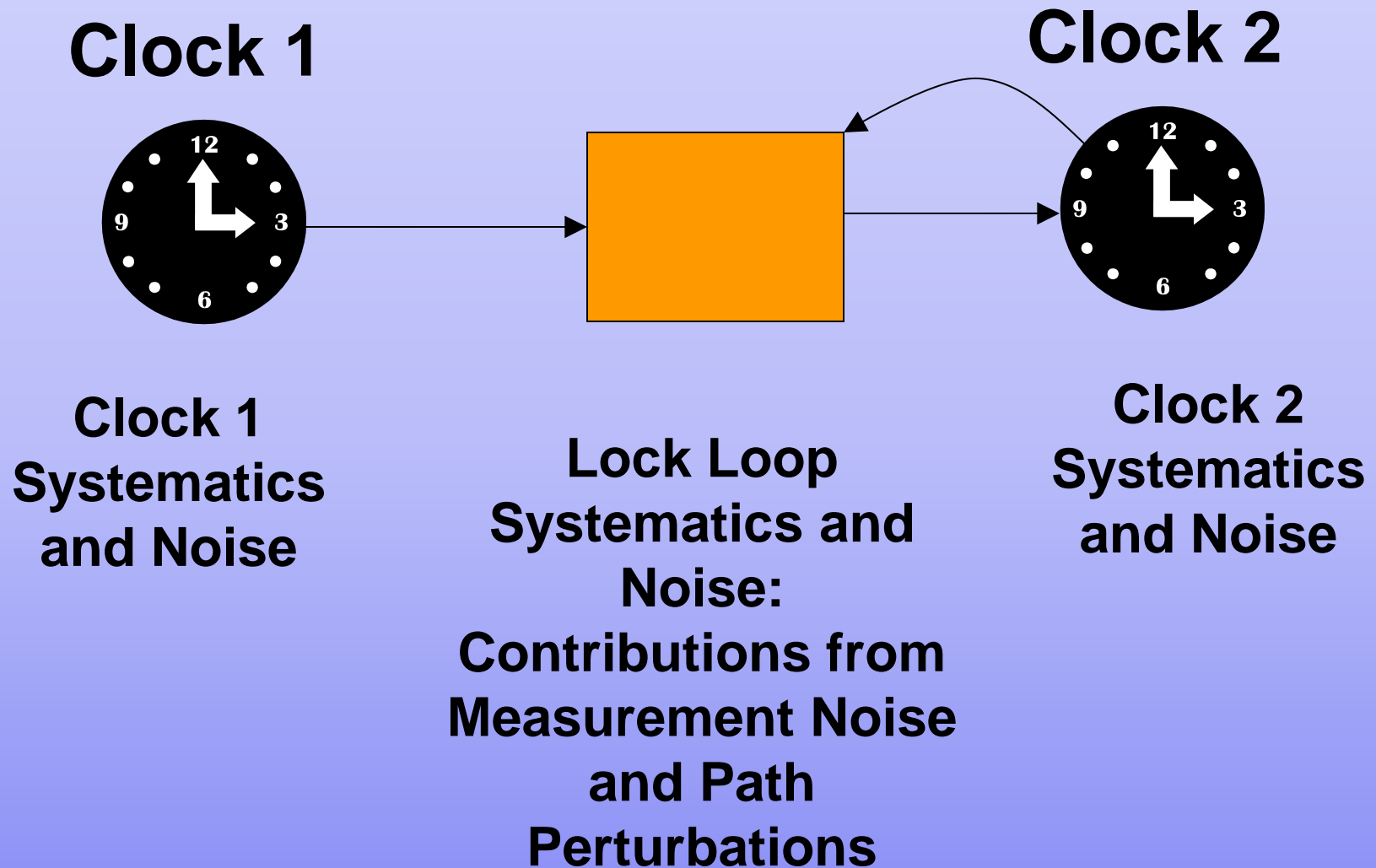
Time and Frequency Transfer

- Accuracy and Stability are the Concerns
 - Time Transfer Accuracy Requires Calibrating Delays
 - Time Stability = Frequency Accuracy
- Continuous vs Intermittent Measurements

Dissemination or Comparison System

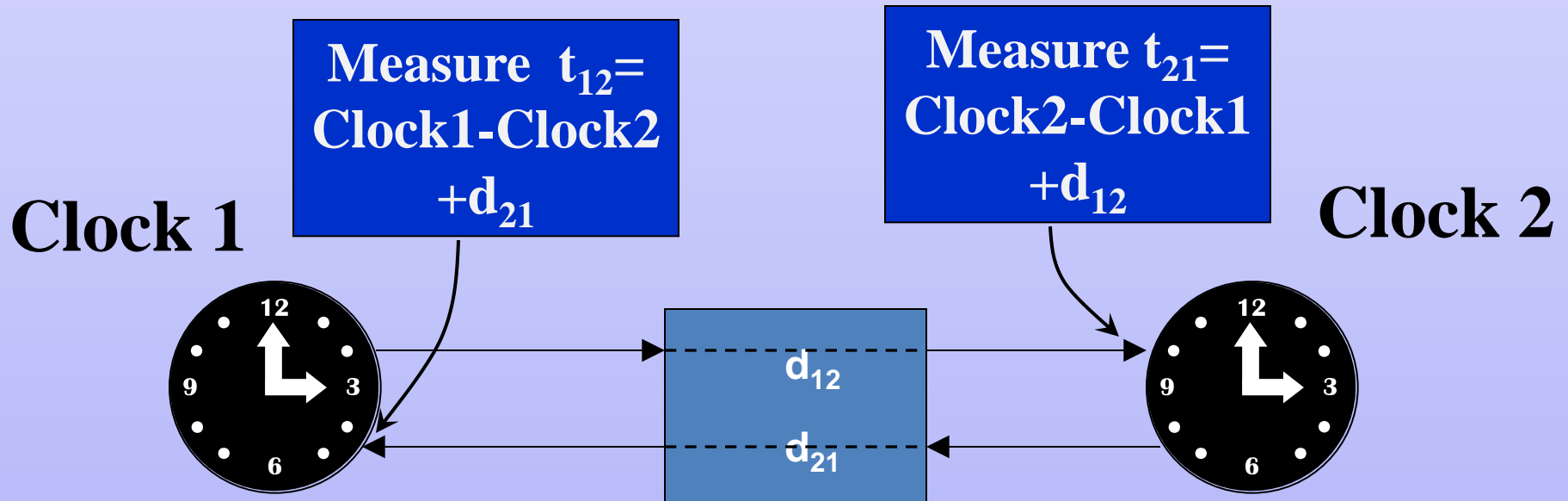


Clock Hierarchies



Two -Way Comparison System

(e.g. IEEE1588 – PTP)



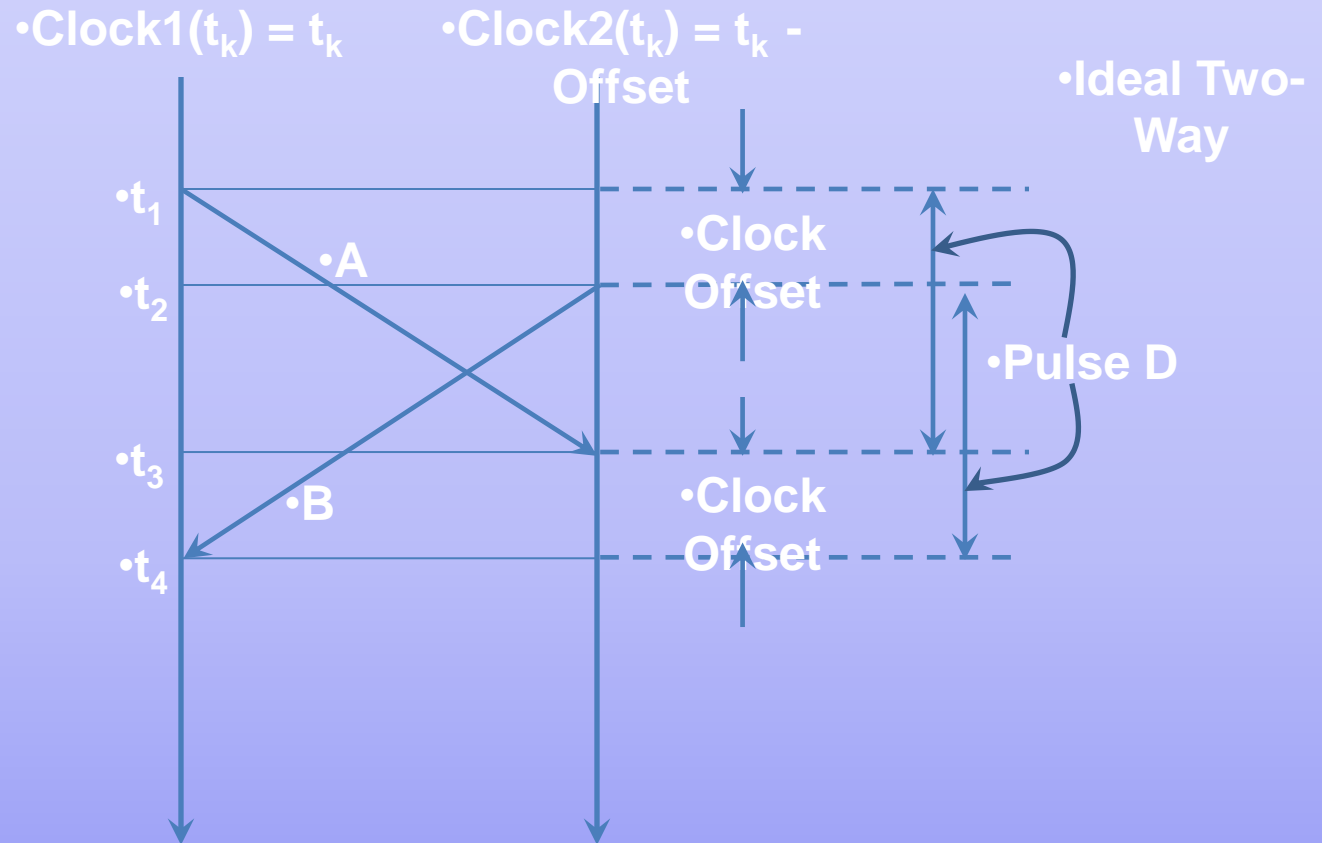
Clock 1
Systematics
and Noise

Measurement Noise
and Path Perturbations
Largely Reciprocal:

$$d_{21} = d_{12}$$

Clock 2
Systematics
and Noise

Two-Way has Four Time Stamps



Ideal Two-Way Computation

- Signal A: $t_{31} = \text{Clock2}(t_3) - \text{Clock1}(t_1)$
- Signal B: $t_{42} = \text{Clock1}(t_4) - \text{Clock2}(t_2)$
- Assume Clock1 is correct, Clock2 has an offset or error E , and Delays, D , are reciprocal
 - $\text{Clock1}(t_j) = t_j$, $\text{Clock2}(t_j) = t_j - E$
 - Transmission times on local clocks: $\text{Clock2}(t_2) = \text{Clock1}(t_1)$, i.e. $t_2 = t_1 + E$
 - Reciprocal Delays: $d_{12} = d_{21} = D$
- Then $t_2 = t_1 + E$, $t_3 = t_1 + D$, $t_4 = t_2 + D$
- Then $t_{31} = \text{Clock2}(t_3) - \text{Clock1}(t_1) = t_3 - E - t_1 = t_1 + D - E - t_1 = D - E$
- And $t_{42} = \text{Clock1}(t_4) - \text{Clock2}(t_2) = t_4 - (t_2 - E) = t_2 + D - (t_2 - E) = D + E$
- Therefore
 - $D = \frac{1}{2} (t_{42} + t_{31})$
 - $E = \frac{1}{2} (t_{42} - t_{31})$

Synchronization vs Syntonization

Two Separate Concepts

Both called “Synchronization” in Telecom

Synchronization

Same Time

Same Phase

Phase Lock

Syntonization

Same Frequency

Frequency Lock \Rightarrow Phase Offset Unbounded

How to Characterize Attributes of Time and Frequency Transfer Systems

1. Time Transfer Accuracy
 1. Agreement with the “true” clock difference
 2. Evaluate with a more accurate transfer system
 3. Never better than stability
2. Time Transfer Stability -- Plot $x(t)$
 1. TDEV, $\sigma_x(\tau)$
 2. Spectrum, $S_x(f)$
3. Frequency Transfer Accuracy
 1. Directly related to time transfer stability
 2. A function of averaging time, τ , and processing
4. Frequency Transfer Stability-- Plot $y(t)$
 1. ADEV, $\sigma_y(\tau)$
 2. Spectrum, $S_y(f)$
 3. Estimate Drift

Summary:

Time and Frequency Transfer Systems

- Time: Calibrate the Delay
- Stability: Keep the delay constant
- Issues
 - Accuracy
 - Stability
 - Uncertainty
 - Systematic vs Random Deviations
- Syntonization vs Synchronization

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GNSS References

- GPS
 - CGSIC 2013 <http://www.gps.gov/cgsic/meetings/2013/>
 - Coast Guard Nav Center <http://www.navcen.uscg.gov/>
- Galileo <http://www.gsc-europa.eu/system-status/Constellation-Information>
- Glonass
<http://www.sdcm.ru/smglo/grupglo?version=eng&site=extern>
- Beidou:
 - IGS page http://igs.org/mgex/Status_BDS.htm
- General
 - GPS World <http://gpsworld.com/>
 - Inside GNSS <http://www.insidegnss.com/>